



ABS M4 Kit

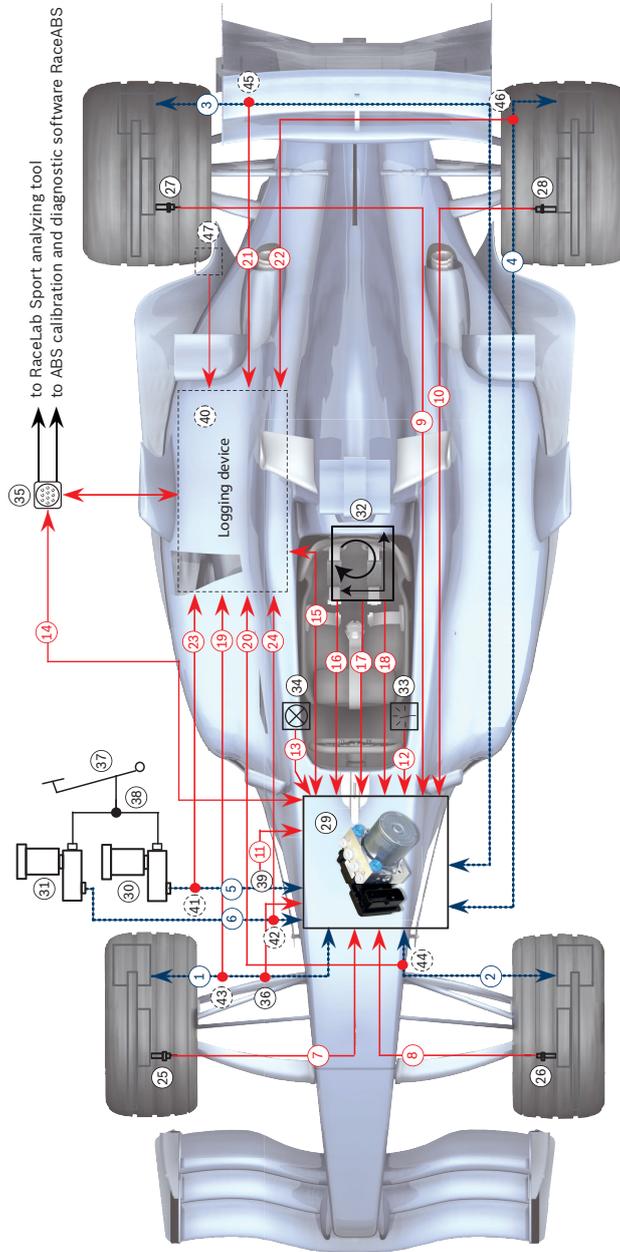
Manual

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1 System Overview



- Optional equipment**
- 40 Logging device
 - 41 Pressure sensor master cylinder front
 - 42 Pressure sensor master cylinder rear
 - 43 Pressure sensor front left
 - 44 Pressure sensor front right
 - 45 Pressure sensor rear left
 - 46 Pressure sensor rear right
 - 47 Steering angle potentiometer

- Hardware**
- 25 Wheel speed sensor front right
 - 26 Wheel speed sensor front left
 - 27 Wheel speed sensor rear right
 - 28 Wheel speed sensor rear left
 - 29 ABS ECU & hydraulic modulator
 - 30 Brake master cylinder front
 - 31 Brake master cylinder rear
 - 32 Yaw/ acceleration sensor
 - 33 ABS map switch
 - 34 ABS Warning lamp (MIL)
 - 35 CAN-Link to C-Sport memory
 - 36 Brake switch
 - 37 Brake pedal
 - 38 Brake balance adjuster
 - 39 Brake pressure sensor

- Measuring channels optional**
- 19 Signal brake pressure front right
 - 20 Signal brake pressure front left
 - 21 Signal brake pressure rear right
 - 22 Signal brake pressure rear left
 - 23 Brake pressure master cylinder front
 - 24 Brake pressure master cylinder rear

- Measuring channels**
- 7 Wheel speed front right
 - 8 Wheel speed front left
 - 9 Wheel speed rear right
 - 10 Wheel speed rear left
 - 11 Signal brake pressure sensor
 - 12 Signal function switch
 - 13 ABS Warning Lamp (MIL)
 - 14 K-line to diagnostic connector
 - 15 CAN-Link to C-Sport memory
 - 16 Signal longitudinal acceleration via CAN
 - 17 Signal lateral acceleration sensor via CAN
 - 18 Yaw signal via CAN

- Brake lines**
- 1 Brake pressure front right
 - 2 Brake pressure front left
 - 3 Brake pressure rear right
 - 4 Brake pressure rear left
 - 5 Brake pressure master cylinder front
 - 6 Brake pressure master cylinder rear

2 Before Use

Read these instructions carefully and follow the recommendations for use step by step. We are happy to give you additional notes and explanations. Our contact information is on the back cover of this manual.

2.1 Safety Information

The Bosch Motorsport Kit was developed for use by professionals and requires in depth knowledge of automobile technology and experience in motorsport. Using the system does not come without its risks.

It is the duty of the customer to use the system for motor racing purposes only and not on public roads. We accept no responsibility for the reliability of the system on public roads. In the event that the system is used on public roads, we shall not be held responsible or liable for damages.

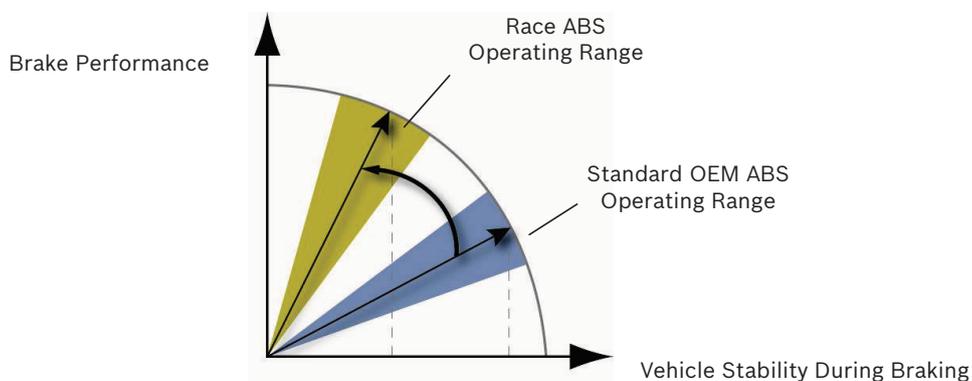
Any maintenance or repair must be performed by authorized and qualified personnel approved by Bosch Motorsport.

All system parts are designed to work together and may not be replaced with similar parts without our expressed permission (this includes the wiring harness). For first time purchases, each team or owner must purchase a complete kit which includes a wiring harness. Spare parts may be purchased after a complete kit has been purchased. The use of unauthorized parts or wiring harnesses will not be supported by Bosch Motorsport; additionally the system cannot be guaranteed to work properly and/or without limitations.

It is essential that the predefined Bosch Motorsport assembly guidelines are complied with, see section Assembling the Parts [► 19], the system to run properly. This applies above all for installing the MIL (malfunction indication lamp) within the driver's range of visibility.

2.2 ABS in Motorsport

The ABS function is a compromise between drivability and braking performance. Drivability is the primary focus for passenger based vehicles. The ABS is designed to keep the passenger vehicle maneuverable and stable under any circumstances and under any conceivable driving conditions.



In a motorsport context, this compromise shifts towards braking performance, as experienced drivers can still control a slightly unstable vehicle. Together with different tire structures and higher braking potential, a racecar is capable of greatly

increased deceleration rates. To consider different chassis tuning and tires ABS M4 Kit has nine control settings. They differ from each other belonging start and process of control. With this, the driver can choose the best setting for his vehicle. Furthermore, the ABS provides the opportunity to program two individual control settings for you vehicle. For calibration drives, the ABS function can be deactivated separately, whereby all ABS sensor signals are transmitted and processed furthermore.

2.3 Principle of Operation

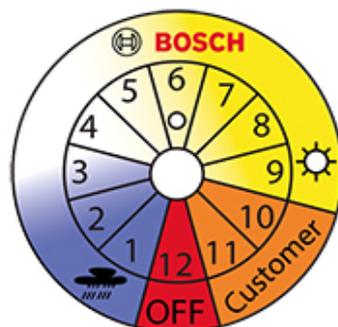
ABS M4 is suitable for **front-wheel, rear-wheel and four-wheel drive vehicles**. It is based on a series production ABS and adapted in years of development work to meet motorsport requirements.

The ABS prevents the wheels from locking during braking. It does this by constantly measuring the individual wheel speeds and comparing them with the wheel speeds predicted by the system. If, during braking, the measured wheel speed deviates from the system's predicted wheel speed, the ABS controller takes over, correcting the brake force to keep the wheel at the optimum slip level and so achieving the highest possible deceleration rate. This is carried out separately for each wheel.

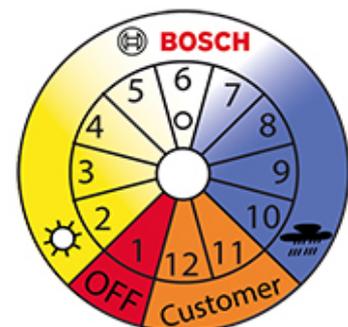
When the brake force is reduced by the ABS, brake fluid is released from the brake caliper and fed into the pressure reservoir of the hydraulic power unit of the ABS. The hydraulic power unit then feeds the fluid back into the master cylinder via a piston pump driven by an electric motor. The driver can hear this return pumping of the brake fluid and feel the response of the brake pedal.

2.4 Features

Note: In the following, we only refer to the Standard ABS scale. The Alternative ABS scale is only used for DF11S, 1 Mbaut. You can use the Alternative ABS scale if your ABS M4 Kit is switched off in position 1.



ABS scale standard



ABS scale alternative

- Nine different control settings, selectable via a switch in the cockpit (position 1-9)

The ABS map switch in the cockpit enables the driver to select various control settings stored in the control device. Using the standard ABS scale, it starts with switch position 1 for the most sensitive controller setting (e.g. heavy rain condition). The response characteristic gets more progressive from position to position. Finally, with switch position 9 the most progressive effect is ach-

ieved. With the different control settings, the driver can select the preferable map for the vehicle, the racetrack and weather. Comment: The most progressive braking characteristics leads not necessarily to best lap times. Rather the position that allows the driver to feel the most comfortable will be the most desirable position.

- Two additional vehicle-specific control maps storable (position 10 and 11)
Switch positions 10 and 11 are pre-dated with a copy of position 9. Bosch-Engineers can calibrate them individually for each customer.
- Switch off ABS functions for calibration drives (position 12).
You can switch off the ABS functions by switching to position 12. This can be very helpful, e.g. for calibration of the brake balance adjuster. All ABS sensor signals will still be communicated. Every older ABS M4 Kit Kit can be updated to this function. During warm-up we recommend to choose position 12. Since software status V1017 no error entry takes place any longer.
- Measuring vehicle dynamics
Due to specially-adapted chassis and tires, motor racing vehicles allow for significantly higher longitudinal and lateral acceleration rates than series production vehicles. The ABS M4 Kit is designed to intervene after a corresponding amount of time. Our ABS M4 Kit sensors constantly measure vehicle acceleration and rotation rates as well as the pressure of the front brake circuit. The ABS control algorithms at the front brake circuit rely on the measurements of acceleration and pressure.
- Programming and diagnosis software
Each ABS M4 Kit Kit is preprogrammed with specific data related to the vehicle, such as vehicle mass, wheelbase, track width, tire rolling circumference, etc. Should the vehicle data change at any time, you can adapt the system settings by using the RaceABS diagnostic software. You find the software for free download on our website www.bosch-motorsport.de.
- There are further features to the software:
 - Performing a system function test
The system function test can diagnose the functional capability and professional assembly of any part, without having to move the vehicle.
 - Reading data from the error log
Any missing part or incorrectly connected electrical connection is signaled by a lit MIL (Malfunction Indication Lamp). In the error log you can read and analyze what errors have set the MIL and then delete the errors after the issue has been resolved.
 - Repair Bleeding Wizard
Step-by-step instructions will guide you through bleeding the ABS unit.
 - Connectivity for data loggers and display
You can connect a data logger (e.g. the C 50 from Bosch Motorsport) to the ABS-Wiring-Harness via CAN. The CAN Bus can give you wheelspeeds and other readings from the system. All ABS M4 Kit CAN messages can be displayed on any programmable, CAN-compatible display (e.g. the DDU 7 from Bosch Motorsport).
 - Switch on and off the system with a switch in the cockpit
You can switch the system ON or OFF by moving the switch in the cockpit for one time.

- Reset the System with a switch in the cockpit
You can reset the system by moving the switch to the position OFF and then directly again ON.

See also

 Repair Bleeding Wizzard [[▶ 35](#)]

3 Technical Data

Mechanical Data

Hydraulic unit with attached ECU	
Serial housing, dust- and damp-proof	
Vibration damped circuit board	
38 pin connector	
2 hydraulic valves per wheel	
2 brake circuits (front and rear)	
2 hydraulic high pressures pumps	
2 hydraulic accumulators 3 cm ³ /each	
Standard fittings	2 x master cylinders M12 x 1 4 x brake cylinders M10 x 1
Size	125 x 80.3 x 129.6 mm
Weight	about 1,850 g
Operating temperature	-30 to 130°C
Max. shock	50 g less than 6 ms

Electrical Data

Supply voltage	8 to 16 V, max. 26 V for 5 min
Max. peak voltage	35 V for 200 ms
Power consumption	8 W stand-by, 230 W in operation
Inputs	
4 active wheel speed DF11	
Brake pressure (front brake circuit)	
Longitudinal acceleration, lateral acceleration, yaw rate	
9 adjustment settings applicable for OEMs (Pos. 1-9)	
2 adjustment settings applicable for Teras (Pos. 10 and 11)	
ABS function can be deactivated (Pos. 12)	
Brake light switch	
Outputs	
ABS warning light (MIL)	
Communication	
CAN interface	

Content of Kit and Weights

Hydraulic unit with attached ECU	About 1,850 g
Pressure sensor	About 40 g
Yaw/acceleration sensor	About 60 g

12 position function switch	About 50 g
4 wheel speed sensors DF11 standard	About 50 g/each
ABS warning light (MIL)	About 50 g
Vehicle specific wiring harness with motorsport connectors	Depends on version
Clubsport wiring harness	About 1,500 g
Mounting and vibration-damping boards	About 80 g
Mounting board for hydraulic unit	About 210 g

Optional Accessories

Data logger C 50	F 02U V01 164-01
Data logger C 60	F 02U V00 875-03
Display DDU 7	F 02U V01 130-04
Communication interface MSA Box II	F 02U V00 327-02
Wheel speed signal splitters	
Quad with 2 motorsport connectors	F 02U V00 203-03
Quad with 1 motorsport connector	F 02U V00 335-03
Porsche 991 with 1 motorsport connector	F 02U V01 928-01

Field of application

ABS for front-wheel, rear-wheel or four-wheel drive racing cars

Part numbers

ABS M4-Package 1 (incl. wiring harness with motorsport connectors, individual layout depending on customer requirements, wheel speed sensors with production-type connectors)	F 02UV00 289-01
ABS M4-Package 2 (incl. wiring harness with motorsport connectors, individual layout depending on customer requirements, wheel speed sensors with motorsport connectors)	F02U V00 290-01
ABS M4-Package Clubsport (incl. wiring harness with motorsport connectors, wheel speed sensors with serial connectors)	1MBaud: F 02U V01 289-49 (DF11S) F 02U V00 543-13 (DF11i) 500 kBaud: F 02U V01 289-48 (DF11S) F 02U V00 543-12 (DF11i)

4 Adaptations to Your Vehicle

Physical vehicle data

For optimum brake performance, each M4 unit has to be customized to suit the vehicle in which it is to be used. To do this, the system can be programmed by the user with certain data, such as the vehicle weight, vehicle dimensions, wheel circumference, and wheel weight. The system then uses this data as basis for calculation. Bosch can also program this data ahead prior to delivery on request, however, it is very important that you calibrate or verify the data prior to operating the vehicle.

You can find a form to fill in your vehicle data on www.bosch-motorsport.com. This form should be provided to you by your dealer with the order of the kit, if the kit shall be programmed by Bosch.

Wiring harness

Each ABS system is delivered with a wiring harness that we have specifically created in accordance with customer requests.

With every Clubsport ABS you receive an appropriate wiring harness, which is not specifically created. Please see --- MISSING LINK ---.

System environment and related requirements

Is the ABS system being used as a closed stand-alone system? Or is it networked with a control unit?

If the system is networked with a standard control unit, we recommend that you use our speed/acceleration sensor with a CAN rate of 500 Kbaud/s to avoid compatibility issues.

If the system is networked with a motorsport control unit or used as self-sufficient stand-alone-system, we recommend that you use our speed/acceleration sensor with a CAN rate of 1 Mbaud/s. This version features a greater measuring range.

Was or is the vehicle already fitted with an ABS system? Was or is it an old BOSCH ABS system?

The requires signals from differential dual Hallsensors such as the Bosch DF11 or similar to function correctly. These sensor types are used in new vehicles for ABS and ESP® systems and can be carried over for the . The signal level of conventional speed sensors, as found in old series-production ABS systems for example, is not compatible with the ; it is therefore not possible to carry over conventional speed sensors as signal transmitters.

If your vehicle contains an older ABS system, you have to remove the wheel speed sensors and replace them by the sensors includes in the package to be able to use the .

If you are fitting your vehicle with an ABS system for the first time, you may need an encoder wheel for each wheel and a sensor mount to record the wheel speeds. Please pay attention to the fitting position of the wheel speed sensors.

Do the wheel speed signals also need to be made available to other control units?

We have developed a wheel speed signal splitter that converts the signals in such a way that they can also be processed by peripheral engine control units and data logging systems. The splitter provides an input signal like as it is shown in the diagram in chapter --- MISSING LINK ---. This module can be used, for traction control, display and gear units. For ordering information see also --- MISSING LINK ---.

See also

-  [Wheel Speed Signal Splitter \[▶ 17\]](#)
-  [Wiring Harness Clubsport \[▶ 53\]](#)

5 Included in the Kit

The following chapter introduces the contents of the different kits.

5.1 ABS M4 Kit 1

ABS M4 Kit 1 with part number F 02U V00 289-01 always includes a wiring harness. ABS M4 Kit 1 includes the following parts, which are also available as individual spare parts (Hydraulic power unit only in exchange):

Description	Part Number
Hydraulic unit with attached ECU	Standard (for DF11S wheel speed sensors): F 02U V00 866-01 Alternativ (for DF11i wheel speed sensors): F 02U 002 487-01
Mounting plate for hydraulic unit with attached ECU	0 265 Y44 520-01
Brake pressure sensor	0 261 B08 072-08
4 wheel speed sensors DF11	0 265 008 022 0 285 007 871 (old model)
Yaw/acceleration sensor	Standard 1 MBaud/s: 0 265 005 838 Alternative 500 kBaud/s: F 02U V00 049-02
Damping plate for yaw/acceleration sensor	1 271 032 390
12-position ABS map switch	F 02U V00 111-03
ABS warning light (MIL) with electronic control module	Bulb: F 02U V00 112-01 LED: F 02U V00 112-02
Incl. wiring harness with motorsport connectors, customer-specific layout, wheel speed sensors with production-type connectors.	Similar to connection diagram F 02U S00 043-09, see Wiring Diagram ABS M4 [50]

5.2 ABS M4 Kit 2

ABS M4 Kit 2 includes all the parts from Kit 1, with the exception of a different wiring harness with motorsport connectors for the wheel speed sensors.

5.3 ABS M4 Kit Clubsport

There are a few variants of the ABS M4 Kit Clubsport available:

Description	Part Number
ABS M4 Kit Clubsport (1 MBaud, DF11S)	F 02U V01 289-49
ABS M4 Kit Clubsport (500 kBaud, DF11S)	F 02U V01 289-48
ABS M4 Kit Clubsport (1 MBaud, for DF11i)	F 02U V00 543-13
ABS M4 Kit Clubsport (500 kBaud, for DF11i)	F 02U V00 543-12

ABSM4 Kit includes all parts from Kit 1, but a different wiring harness, which cannot be modified. By default the wiring harness includes a 60 Ohm terminal resistance, which can be replaced customer specific by a 120 Ohm or deleted completely, see wiring diagram ABS M4 Clubsport.

Description	Part Number
Wiring harness Clubsport	F 02U V01 917-01

See also

 [Wiring Diagram ABS M4 Clubsport \[▶ 51\]](#)

5.4 Connector Overview Kit 1

ABS M4 Kit 1 with part number F 02U V00 289-01 includes the following connectors, which are also available as individual spare parts:

Connector for	Part Number
Attached control unit connector	Standard wire departure on top: F 02U B00 238-01 wire departure on top 90°: F 02U B00 238-01 Alternativ wire departure on bottom: F 02U B00 237-01 wire departure on bottom 90°: F 02U B00 237-01
Brake pressure sensor Compact 3-pin connector	D 261 205 335-01
12-position ABS map switch ASL 006-05SE-HE	F 02U 000 230-01
ABS warning light (MIL) ASL 006-05SA-HE	F 02U 000 226-01

Connector for	Part Number
Wheel speed sensor Tyco 2-pin connector	F 02U B00 241-01
Yaw/acceleration sensor Tyco 4-pin connector	F 02U B00 435-01
Diagnosis connector K-line	F 02U 000 258-01
Wheel speed signal splitter ABS-sided AS 612-35 SN	F 02U 000 443-01
Jumper connector for wiring harness without wheel speed module AS 112-35 PN	F 02U 000 304-01 or F 02U B00 354-01
Data-logger intersection ASL 006-05SD HE	F 02U 000 229-01

Mating connector overview ABS M4-Paket 1

Connector for	Part Number
Brake pressure sensor	D 261 205 335-01
12-position ABS map switch	F 02U 000 230-01
ABS warning light (MIL)	F 02U 000 226-01
Wheel speed sensor	F 02U B00 241-01
Yaw/acceleration sensor	F 02U B00 435-01

5.5 Connector Overview Kit 2

ABS M4 Kit 2 with part number F 02U V00 290-01 includes a harness with all the connectors from Kit 1, with the exception of different connectors for the wheel speed sensors:

Connector for	Part Number
Wiring harness sided ASL 006-05PN-HE	F 02U 000 342-01
Sensor sided ASL 606-05SN-HE	F 02U 000 416-01

5.6 Connector Overview Kit Clubsport

ABS M4-Kit Clubsport with part numbers F 02U V01 289-49, F 02U V01 289-48, F 02U V00 543-13 or F 02U V00 543-12 includes all connectors of Kit 1, but differently the encoding connector:

Anschlussstecker für	Teilenummer
Encoding connector CAN wiring harness- sided Super Seal 2-pole	F 02U B00 246-01

Anschlussstecker für	Teilenummer
Encoding connector CAN with a 60 Ohm resistor Super Seal 2-pole	F 02U B00 247-01

6 Optional Accessories

The following chapter introduces the optional accessories for the ABS Kit, which are not included in the kit.

6.1 MSA Box II

ABS M4 communicates with your laptop via the MSA Box II. It has a USB connection to the laptop and a motorsport connector to interface with the ABS M4 wire harness. Communication via K-line.

Description	Part Number
MSA Box II	F 02U V00 327-03

6.2 Wheel Speed Signal Splitter

The from Bosch Motorsport relies on specifically-designed wheel speed signals, delivered exclusively from active speed sensors, e.g. from the Bosch DF11 family. These sensors are used in current ABS and ESP® systems. The four speed sensors included in the Kit meet this classification. The signal of a regular speed sensor, as found in older series production ABS applications, is not compatible with ; they could not be used as signal providers. It is an "open collector" signal which grounds the voltage at the ECU input with every flank. Bosch Motorsport has developed a wheel speed signal splitter that converts the sensor signals in such a way that they can be processed by peripheral ECUs and data recording systems. This signal splitter is available e.g. for measuring vehicle speed or traction control. The signals of the different wheel speed signal splitters:

	Input signal	Output signal
F 02U V00 203-03 F 02U V00 335-03	14 mA 7 mA	Ux V 0 V
F 02U V01 928-01	14 mA 7 mA	14 mA 7 mA

Description	Part Number
Wheel speed signal splitter quad with 1 motorsport connector	F 02U V00 335-03
Wheel speed signal splitter quad with 2 motorsport connectors	F 02U V00 203-03
Wheel speed signal splitter Porsche 991 with 1 motorsport connector	F 02U V01 928-01

Notice

The wheel speed signal splitter with 1 connector cannot be used with the standard wiring loom design without changes in the layout.

6.3 Data Logger C 70

All data can be stored on a CAN-compatible data logger. We recommend to use our C 70 data logger for storing data.

Bosch Motorsport provides a standardized CAN log in DBC format for analyzing recorded CAN data, see chapter ABS_M4.dbc.

Description	Part Number
Data Logger C 70	F 02U V02 302-01

6.4 Display DDU 9

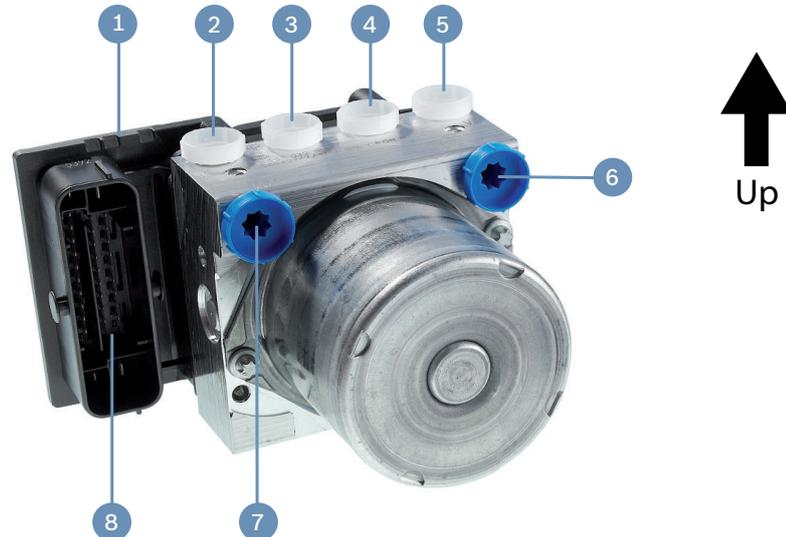
The display DDU 9 has an internal data store with a capacity of 3 GB and can substitute an external data logger. Therefore you need no additional data logger if you use DDU 9.

Description	Part Number
Display DDU 9	F 02U V02 300-022

7 Assembling the Parts

The following chapter introduces the parts of the ABS Kit.

7.1 Hydraulic Power Unit with attached Control Unit



- | | |
|---|-------------------------------------|
| 1 Hydr. Power Unit with attached Control Unit | 5 VL = Brake cylinder front left |
| 2 HL = Brake cylinder rear left | 6 HZ1 = Brake master cylinder front |
| 3 HR = Brake cylinder rear right | 7 HZ2 = rake master cylinder rear |
| 4 VR = Brake cylinder front right | 8 Connector |

The hydraulic power unit with attached control unit has six hydraulic connections — two for the two master cylinders (one each for the front and rear axles) and four for the brake lines.

Caution

The hydraulic power unit is prefilled with brake fluid. During assembly, make sure as little brake fluid as possible is lost.

When installing the hydraulic power unit, make sure the brake line connections are facing upwards to ensure air can be bled out to the brakes. Secure the hydraulic power unit to the assembly plate supplied with the Kit using the three M6x1 screw threads on the underside of the casing. To reduce vibration, rubber pads should be fitted between the assembly plate and the vehicle chassis. To allow easy connection of the main ABS ECU connector, maintain a 10 mm distance between the vehicle chassis and the bottom of the assembly plate.

Notice

Correct position for installation – brake line connections should face upwards.

Install with rubber pads/blocks to reduce vibration.

Leave 10 mm or larger gap in between the vehicle chassis and bottom of assembly plate.

Hydraulic power unit is already filled with brake fluid.

For more on assembly: See Offer Drawing: Hydraulic Power Unit with attached Control Unit [▶ 45].

Notice

Conform to FIA rules

With only 8 valves the ECU fulfills the FIA requirements for GT 3.

7.2 Brake Pressure Sensor



The brake pressure sensor is installed into the front axle brake circuit between the master cylinder and the hydraulic power unit. The sensor is metric thread, M10x1. Before assembly, fill the sensor with brake fluid, e.g. with a small medical syringe. So the brake system can be fully bled, the measuring hole of the brake pressure sensor should point upwards.

Notice

Only use the supplied brake pressure sensor, otherwise will be destroyed.

Install into the front axle brake circuit between the master cylinder and the hydraulic power unit as far away from the power unit as possible to avoid vibration-caused damages.

Fill sensor with brake fluid before installing.

For more on assembly: See Offer Drawing: Brake Pressure Sensor [▶ 46].

7.3 Wheel Speed Sensors



Bosch Motorsport ABS M4 needs special edited wheel speed signals, which are supplied only from active speed sensors like e.g. from Bosch DF11-family. These double hall sensors operate on the differential principle. The ABS M4 needs all

four speed sensors to function; otherwise the system assumes there is an error and shuts down. You should therefore only use the speed sensors as supplied in the ABS M4-Kit (see section --- MISSING LINK ---). We can offer different DF11 versions on request for specific vehicle designs. Existing mounted wheel speed sensors can be tested and approved by us.

Pay attention to the polarity when you are connecting wheel speed sensors.

The sensor must be installed in the right direction, i.e. the encoder wheel and sensor must lie in the defined installation position (fixation screw in rotation position of the encoder wheel). The sensor will not work if it is installed in a position other than the recommended installation position. Make sure the sensor is mounted and secured as tight as possible to prevent sensor errors or failures from vibration. You can find the sensor's dimensions and how to install the sensor on --- MISSING LINK ---.

Notice

User only differential sensors, like Bosch DF11 or similar.

Securely mount sensors and pay attention to correct mounting position (sensors direction sensitive). Sensor holder as stiff as possible.

Sensor measures and implementation of sensor holder you can also find in the --- MISSING LINK ---.

See also

 Wheel Speed Signal Splitter [▶ 17]

 Offer Drawing: Wheel Speed Sensor [▶ 48]

7.4 Encoder Wheel

Encoder wheels usually have 48 teeth. The tooth/gap ratio should be approx. 50 % and the teeth should be approx. 3 mm in height. The encoder wheel must be made of a ferromagnetic material. If required, Bosch Motorsport can provide technical documentation on positioning the encoder wheel. See the back cover of this booklet for our contact information.

7.5 Distance between the Sensor and the Encoder Wheel

You can adjust the distance between the sensor and the encoder wheel to fit the encoder wheel's dimensions and other installation conditions, but gap is normally between 0.8 ± 0.1 mm.

Notice

User a ferromagnetic incremental wheel.

Leave a 0.8 ± 0.1 mm gap between sensor and encoder wheel.

For more on assembly: See the outline drawing on Offer Drawing: Wheel Speed Sensor. [▶ 48]

7.6 Gyro/Acceleration Sensor



The gyro/acceleration sensor is specific to the system and should be mounted as close as possible to the center of gravity of vehicle. The sensor should be assembled with the supplied damping plate. Position the sensor so that the connector is pointing towards the rear of the vehicle.

Notice

Only use the provided kit sensor.

Use the damping plate.

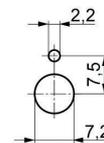
Make sure the sensor is facing the correct direction (see image above).

For more on assembly: See the Offer Drawing: Gyro/Acceleration Sensor [▶ 49].

7.7 ABS Map Switch



**Max. tightening torque:
1-2 Nm!**



Front-panel cut out with locating lug

While driving, the driver can use the ABS map switch to select different control settings and find the optimum setting for his/her driving style. For this reason, make sure the switch is mounted within reach of the driver. Many have found it helpful to fit a diagram showing the current switch position, see also diagram on --- MISSING LINK ---. The switch position is also broadcast on the CAN Bus so it can be displayed with a dash (e. g. the DDU 7 from Bosch Motorsport).

Notice

Only use the supplied ABS Map Switch.

Don't exceed the max. tightening torque of 1-2 Nm. Higher torque will cause stiffness and damage.

See also

📄 Features [▶ 6]

7.8 ABS warning light (MIL)



The included wiring harness is structured in such a way that the power supply to the ABS warning light (MIL) is branched off before the main switch for ABS M4 (terminal 30). This is the only way to ensure that the ABS warning light (MIL) is on when ABS M4 is not working.

Cable length connector to electronic board: 600 mm

Notice

Position the ABS warning light (MIL) so the driver can see it easily.

MIL is on permanent if ABS map switch is in position OFF or the diagnosis software is active.

7.9 Diagnosis Interface



You can connect the a laptop with the optional MSA Box II, see section --- MISSING LINK ---, via the "diagnosis interface" connector. The diagnosis interface connector should be placed so it is easily accessible. You can use programming and diagnosis software, see section --- MISSING LINK ---, to program settings specific to the vehicle and open/delete error messages.

Before using the MSA Box II for the first time you have to install a driver on your laptop, which you can find for free download on our homepage www.bosch-motorsport.de.

See also --- MISSING LINK ---

See also

- 📖 MSA Box II [▶ 17]
- 📖 Programming and Diagnosis Software [▶ 27]
- 📖 ABS M4-Laptop Communication [▶ 26]

7.10 Brake Light Switch

The brake light switch informs the when the driver wishes to brake and therefore functions as a means of plausibility certification for the ABS system. If the brake light switch signal is not available or incorrect, there may be a delay in ABS control.

- If a brake light switch is already fitted in your vehicle:

During braking, the brake light switch emits 12 Volts to pin 30 of the control unit; see the wiring diagram at the end of this manual (Wiring Diagram ABS M4 [► 50]). Terminal 15 on the brake light switch cable remains open.

- If a brake light switch has **not** yet been fitted in your vehicle:

Retrofit a brake light switch if your vehicle does not have one already. In this scenario, terminal 15 supplies the voltage for the brake light switch.

In all cases there must be 12 Volts on pin 30 of the control unit every time the brake light switch is active (driver is braking).

Notice

Pin 30 sends the braking signal to the ABS control unit – always make sure it is connected (12 Volt)!

Terminal 15 remains open if the vehicle already has a brake light switch.

Terminal 15 supplies the voltage to a retrofit brake light switch.

7.11 Brake Lines

Use rigid steel tubes for the brake lines. Use flexible lines only when you have no other option available. This keeps the volume consumption low and the ABS needs less controlling.

The hydraulic unit is secured in the vehicle on the provided mounting plate. During operation, the hydraulic unit will vibrate. These vibrations are then transferred to the brake lines. To prevent vibration-induced damage to the brake lines, they must not be secured at a distance of up to 20 cm from the hydraulic unit so that they can vibrate freely.

Notice

We recommend using rigid metal brake lines; use flexible lines only at points where they are necessary.

Do not secure brake lines 0 to 20 cm from the hydraulic unit.

The unit vibrates and would cause risk of damage to the lines.

Please use brake lines with a minimum inside diameter of 3.2 mm.

7.12 General: Brake Calipers

Use brake calipers that are as stiff as possible. Any flexing will create higher fluid volume consumption. During ABS operation there will be a significantly higher load on the brake piston seals. For this reason, brake piston seals will require more frequent monitoring.

Notice

Monitor brake piston seals more often.

Use brake calipers that are as rigid as possible.

The higher the brake pressure is, the larger is the elasticity of the brake. A blocking pressure of max. 80 bar is optimal.

8 ABS M4-Laptop Communication

The MSA Box II from Bosch Motorsport is the communication interface between and the programming and diagnostic software on your laptop.

Before installing the programming and diagnostic software you need to install the MSA Box II driver.

Installing the MSA Box II driver:

Before using the MSA Box II for the first time you need to install a specific driver on your laptop. Find the driver for free download on our website www.bosch-motorsport.de.

Notice

Please make sure that the MSA Box II is not connected to the laptop while you are installing the driver.

Connect the MSA Box II to the laptop after installing the driver. This will trigger the initial communication between the laptop and the MSA Box II. Follow any prompts that may follow to install the MSA Box II. Once you complete any prompts and computer recognizes the MSA Box II, the MSA Box II is ready for use.

Steps:

1. Unplug the MSA Box II from the laptop.
2. Install the driver.
3. Plug the MSA Box II into the laptop.

9 Programming and Diagnosis Software

The following chapter introduces the programming and diagnosis software.

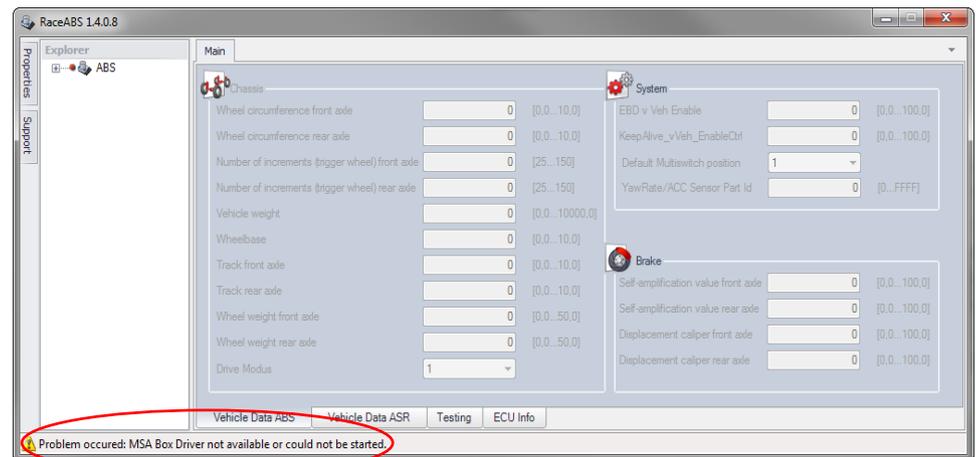
9.1 Installing the Programming and Diagnosis Software

After installing the MSA Box II you need to install the programming and diagnostic software RaceABS 1.1.x. You can find the software including the installation for free download on our website: www.bosch-motorsport.de.

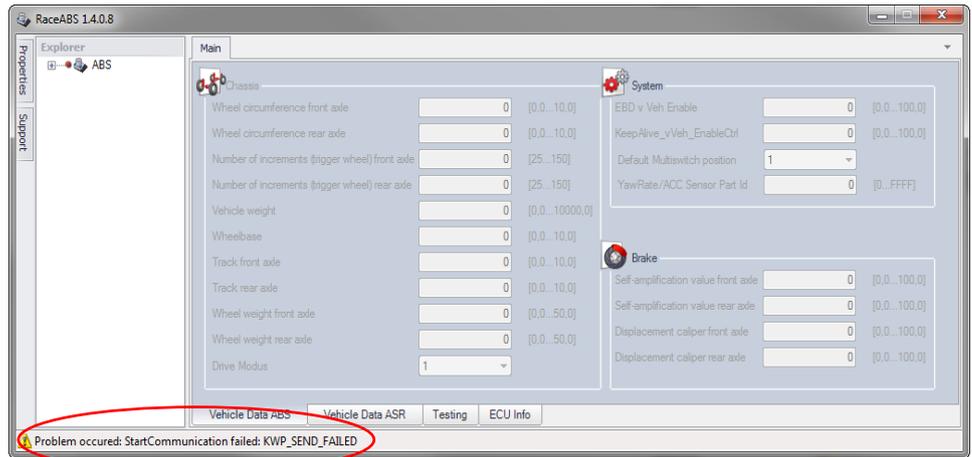
Switch on the ignition

Plug the MSA Box's USB connector into your laptop and its motorsport connector into the wire harness diagnostic interface to enable communication. A green status indicator shows when the connection is successful.

The installation will place an icon on your desktop to the RaceABS software. After the installation is complete, you can launch the application by clicking on the RaceABS icon. If you try to launch the software without the MSA Box II being connected to the laptop, the status indicator in Explorer flashes red and yellow and an error message appears in the status bar:



The following problem message pops up when either the ABS-ECU gets no power supply (e.g. ignition OFF) or the MSA Box II is not connected to the wiring harness. Please make sure that the connection between the diagnosis software and MSA Box II is assured:



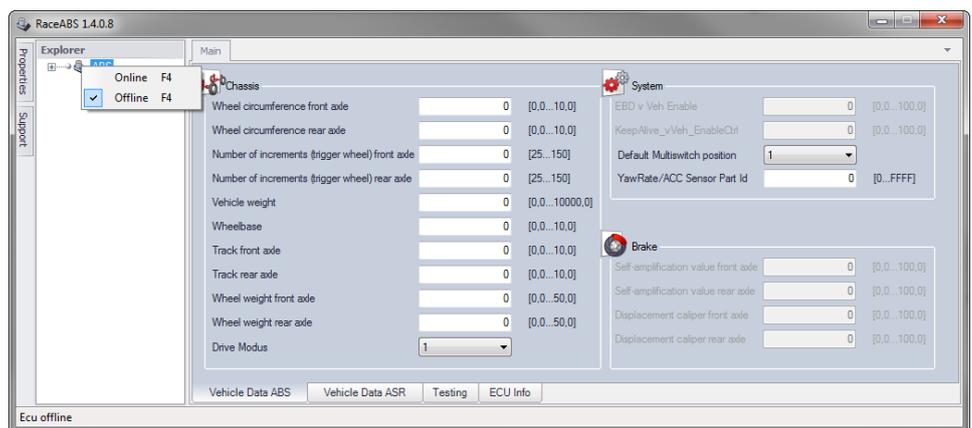
Colors of the status indicator

In online mode, the status indicator can shine in the following colors:

red	no connection
yellow	Connection in progress
	or
	MSA Box II cannot create a connection with the ABS (e.g. ABS switched off)
green	Connection successful
red-yellow flashing	MSA Box II is not connected to Laptop

Change between Online- and Offline-Mode

When no connection exists, it is easier to operate with the diagnosis software in online mode. Please click on the ABS-symbol with the right mouse button to choose between online and offline mode in the status indicator:



Notice

You can only change the status when the ABS tree is closed.

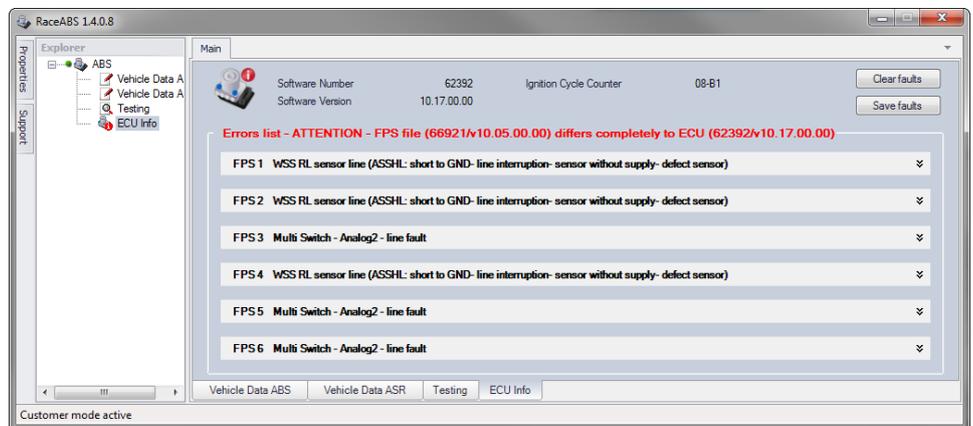
9.2 Features of the Programming and Diagnosis Software

The following chapter introduces features of the programming and diagnosis software.

9.2.1 Properties

The ABS-ECU sends coded data to the diagnosis software. The Fps-File decodes this information and describes the error message as plain text. If you install the software you get the right file, which shows the error message in plain text.

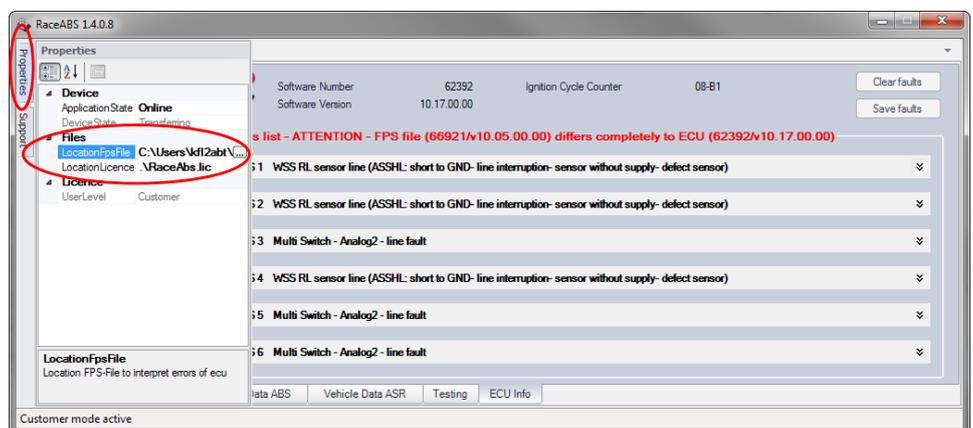
If you don't see plain text or if there is a red colored warning, you do not have the suitable Fps-File to your software.



Please refer to the error message, which software and version of ABS is installed and download the appropriate Fps-File. You can download this at our Home-page, where you can find the most common versions.

If you need a changed and individual adapted version of the diagnosis software, please contact your dealer or the OEM customer service. After that we will deliver you the suitable Fps-File.

To select the file of the diagnosis software, please open the window "properties" on the left side and choose "LocationFPSFile". Click on the quadratic button beside and a new window will open. Allocate the file to the Fps-File.



9.2.2 Support

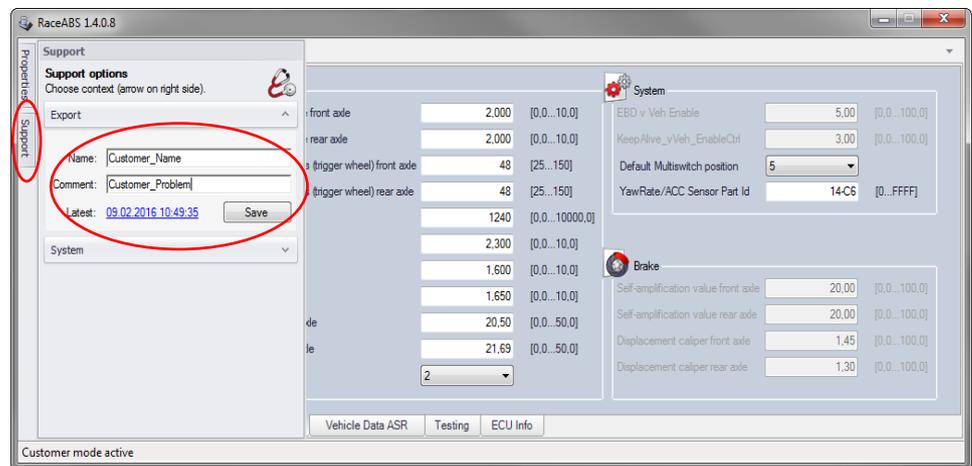
The support section provides an easier handling of the management and the exchange of the ABS-data. To open the support-window, please click on the "Support" button on the left side.

You can execute the following features only in the online modus.

Export

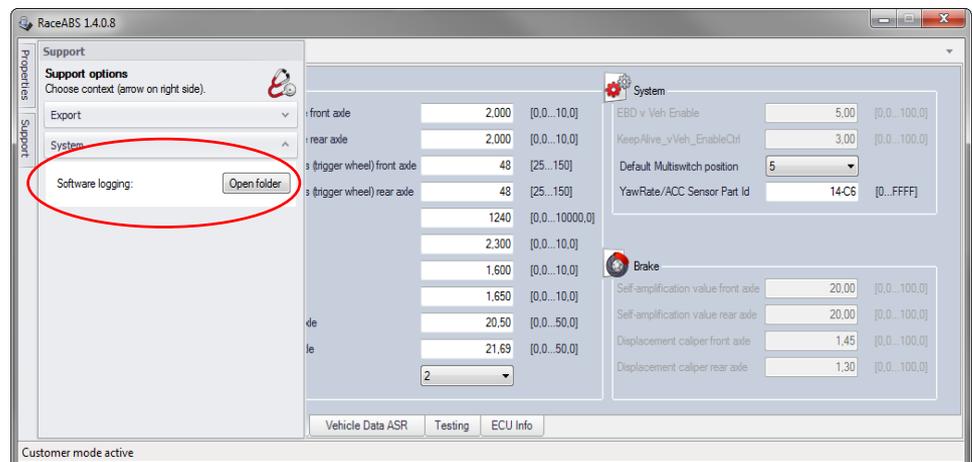
To save the whole settings and error messages (vehicle data ABS, vehicle data ASR, testing, ECU info) simultaneously, fill in a name and a comment in the given fields and click on the button "Save".

If there are problems, you can send the exported file to your dealer or OEM customer service.



System

Please contact your dealer or the OEM customer service if errors occur that you are not able to fix by yourself. In this case, please send a log- and export file. Click on the button "Open folder" to find the log file.

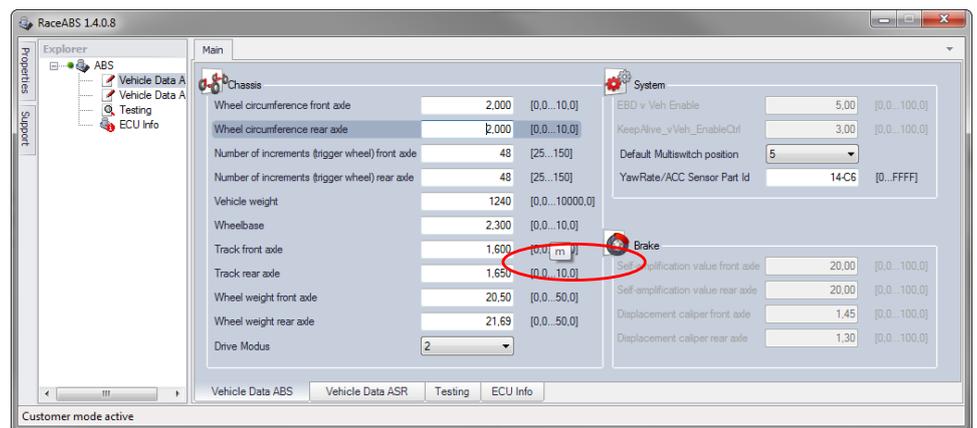


9.2.3 Vehicle Data

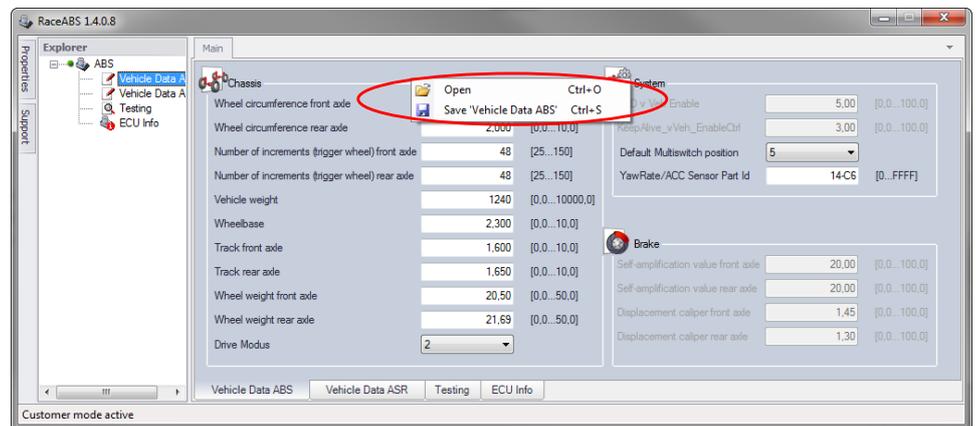
We preprogram each ABS-ECU before delivery. Basis for this preprogramming are the physical data of your vehicle. Prior to delivery, you send us your vehicle data and we will program them in the ABS.

If you need to replace the ECU or modify the programmed vehicle data, you can update the data in the software by yourself.

Within the windows "Vehicle Data ABS" and "Vehicle Data ASR" a short declaration or the measuring unit for each value can be shown. By holding the cursor over a data range, a small window with the declaration occurs.



You can save and open the vehicle data of the windows "Vehicle Data ABS" and "Vehicle Data ASR" separately. Therefore, you click in the window with the right mouse. In this way a text file can be loaded into the system or the actual window can be saved.

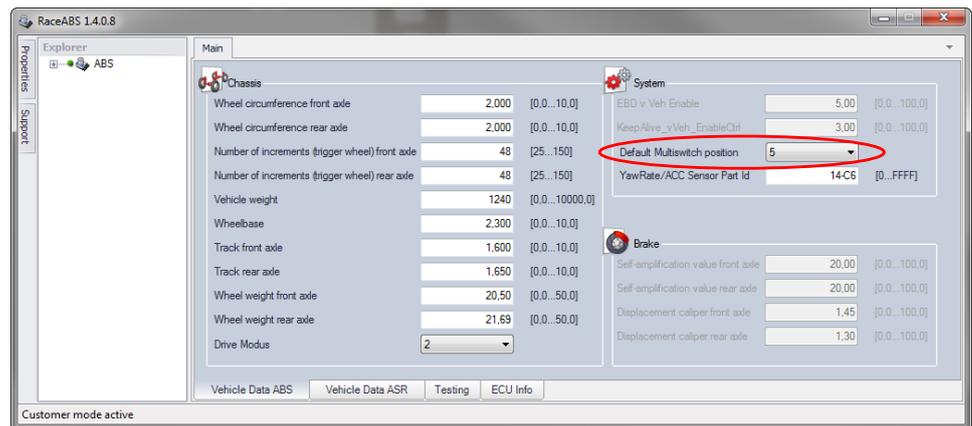


Notice

Only the active window will be saved.

Default value for the ABS map switch

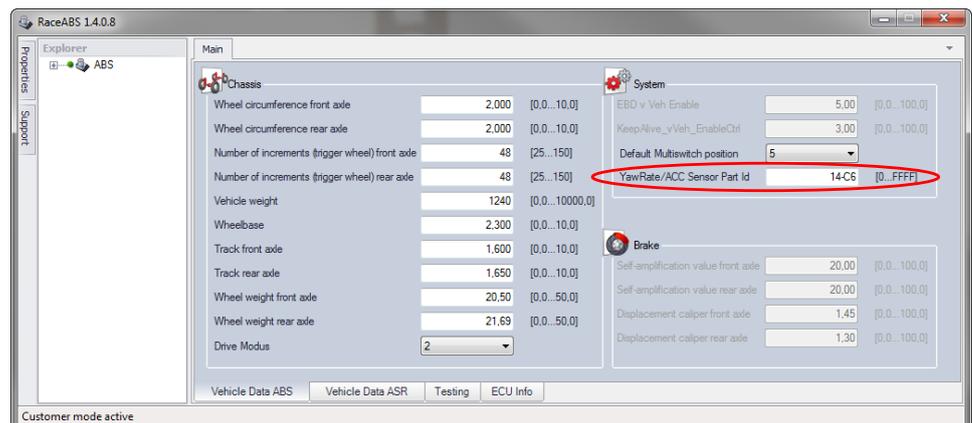
For the 12-position ABS map switch, you can specify a default value. If the function switch breaks down, the switch automatically takes the position of the default value. To assign a position for the default value, select a number between one and twelve in the window "Default Multiswitch position":



YawRate/ACC Sensor Part Id

Each ABS-ECU communicates only with defined sensors. To connect the ABS-ECU with a different sensor, you have to fill in the number of the sensor in the field “YawRate/ACC Sensor Part Id”:

From software number V00906 on you don't have to fill in the sensor number anymore because with the latest software versions the ABS-ECU can adjust to the sensors automatically.



9.2.4 Testing

After assembling the system components you need to carry out a function test before the first test drive. This test will ensure all components (electrical and hydraulic) were assembled correctly and are functioning properly. The vehicle should be placed on four jack stands or on a hoist so that all four wheels can be moved freely. If there is no other option you can lift and test each wheel separately. You will need an assistant to help you check the hydraulic allocation of the wheels.

Step 1: Testing the communication with the ECU

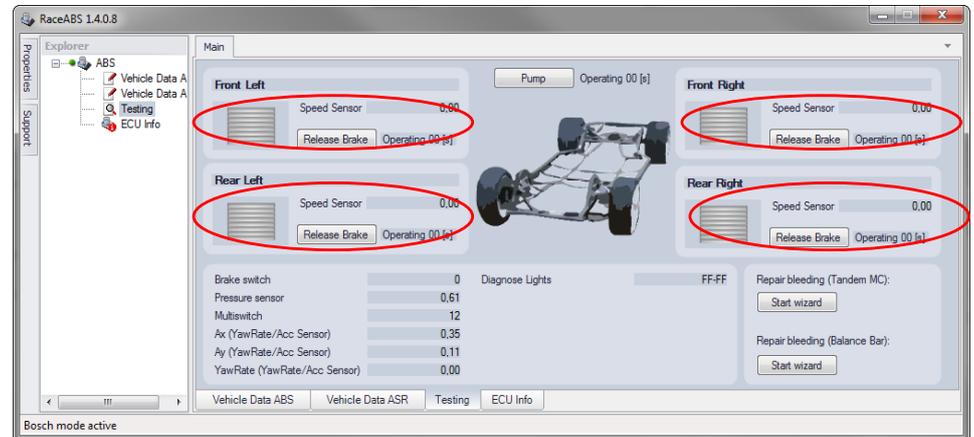
See section ABS M4-Laptop Communication [▶ 26].

Step 2: Testing the indication lamp SILA

When you turn the ignition on, the SILA light turns on briefly and then turns off again. The indication lamp SILA lightens permanently as soon as the RaceABS software is started; see also section ECU Info (Diagnostics) [▶ 36].

Step 3: Testing the correct wheelspeed allocations

With the vehicle jacked up, individually spin all four wheels clockwise and check for the proper front/back, left/right allocation. When you spin each wheel the corresponding position should show a value in the RaceABS software under the "Testing" tab:



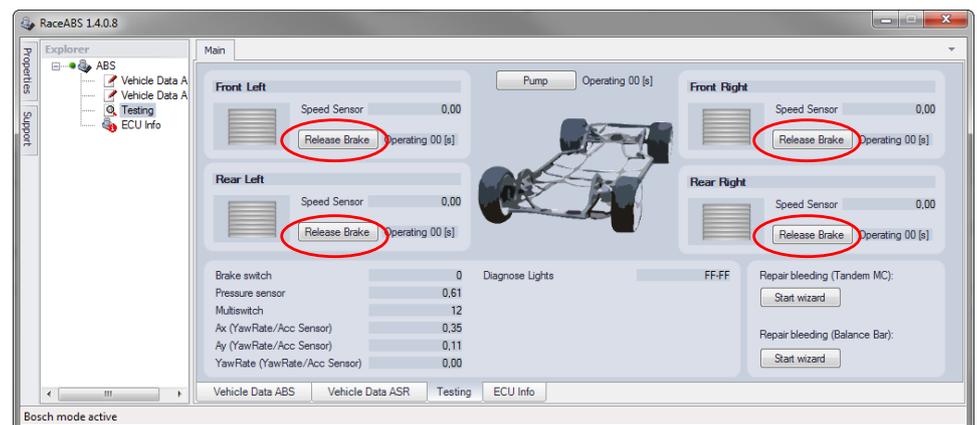
Step 4: Testing the wheels' correct hydraulic allocation

Have an assistant apply the brake pedal and maintain the brake pressure so all four wheels of the jacked up vehicle are locked. Therefore a brake pressure of 15 to 20 bar is sufficient. Unblock successively on wheel and brake after the other by clicking on "Release Brake". The selected wheel must then be able to spin.

Notice

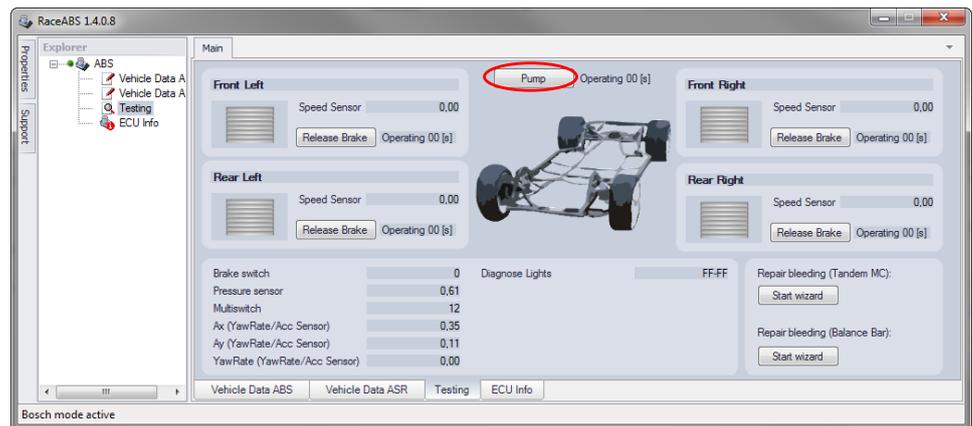
For vehicles with a high blocking effect you have to provide a respectively higher torque to perform the test.

Check the hydraulic allocation for each wheel. Wait for the wheels to be fixed again before continuing with the next step:



Step 5: Testing the electrical pump motor

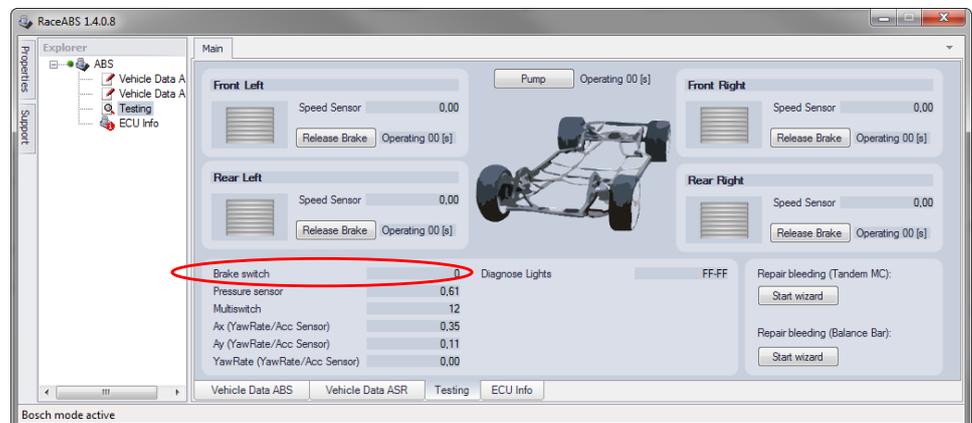
If you click on the "Pump" button, the pump motor should run for 10 seconds or until the same button would be pressed again.



Step 6: Testing the function of the brake pressure sensor and brake light switch

Start the RaceABS with connection to the MSA Box II and press the brake pedal for a few seconds with slowly rising pressure. At a pressure value between 3 and 5 bar the digital display „Brake switch“ bit should toggle from 0 to 1 (see graphic below). Please adjust the brake light switch in an adequate position. If the bit does not toggle, check the switch connection and ensure that it is connected properly, see section Brake Light Switch [▶ 24].

The digital display „Pressure sensor“ should show a logical value, e.g. 3,87 in the screenshot below. If the software displays no value or an illogical value, open the “ECU Info” tab and check the error memory. Do you find errors relating to the brake pressure sensor? See section ECU Info (Diagnostics) [▶ 36] for more information regarding ECU diagnostic errors:

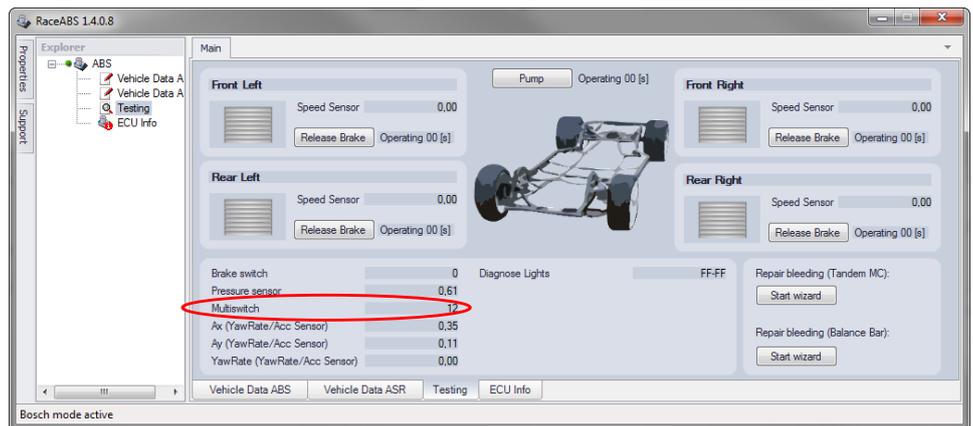


Step 7: Testing the function of the ABS Map switch

Turn the 12-position ABS Map switch through full rotation. Is the “Multiswitch”-Display showing a reaction for each rotary motion? With every clockwise rotation the number of measuring points should increase by 1. ABS warning light (MIL) should shine permanent in switch position 12 (OFF).

Notice

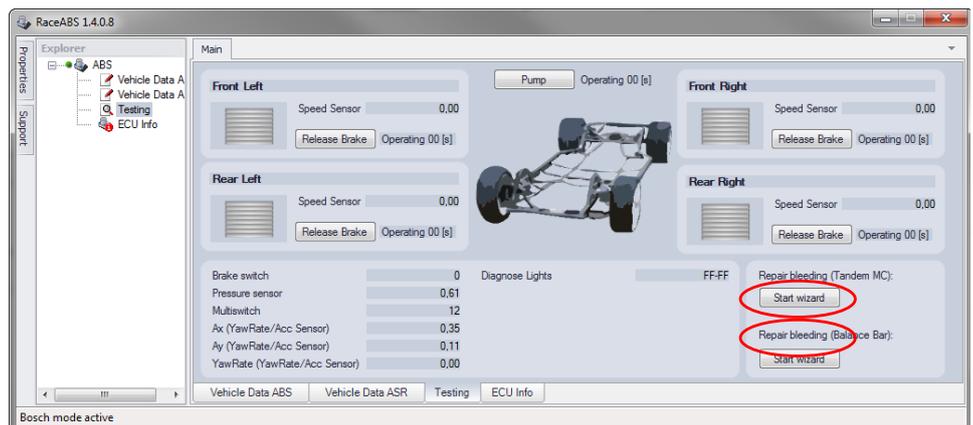
MIL shines permanent in diagnosis mode.



9.2.5 Repair Bleeding Wizzard

Under the "Testing" tab of the RaceABS software you will also find two buttons at the bottom right labeled "Repair bleeding" and "Repair bleeding (Balance Bar)" with the button "Start wizard".

While you bleed your brake system you can choose between the two programs "Repair bleeding" and "Repair bleeding (Balance Bar)":



Notice

The Bleeding Wizzard is only for bleeding the ABS hydraulic power unit. The Bleeding Wizzard is NOT to be used or substituted for bleeding the other parts of the brake system, like lines and brake cylinders. Make sure to bleed these other hydraulic parts of the brake system after bleeding the hydraulic aggregate with the Repair Bleeding Wizzard.

During the ABS bleeding process the brake pedal should be actuated continuously except when opening or closing brake bleeder valves.



Repair bleeding (Tandem MC)

You choose "Repair bleeding (Tandem MC)" if your vehicle executes the same brake pressure to front and rear axle when you actuate the brake pedal.

Click on the button "Repair bleeding (Tandem MC)": a new window will open and leads you step by step through the instruction for bleeding the hydraulic aggregate. You will need an assistant to perform the ABS bleeding procedure.

Repair bleeding (Balance Bar)

You choose "Repair bleeding (Balance Bar)" if your vehicle has a brake balance bar and executes different brake pressure to front and rear axle when you actuate the brake pedal.

Click on the button "Repair bleeding (Balance Bar)": a new window will open and leads you step by step through the instruction for bleeding the hydraulic aggregate. You will need three persons to perform the instruction.

Notice

For vehicles with brake balance bar please open one front and one rear bleeder valve for proper function of the balance bar during the bleeding routine procedure.

9.2.6 ECU Info (Diagnostics)

Indication lamp

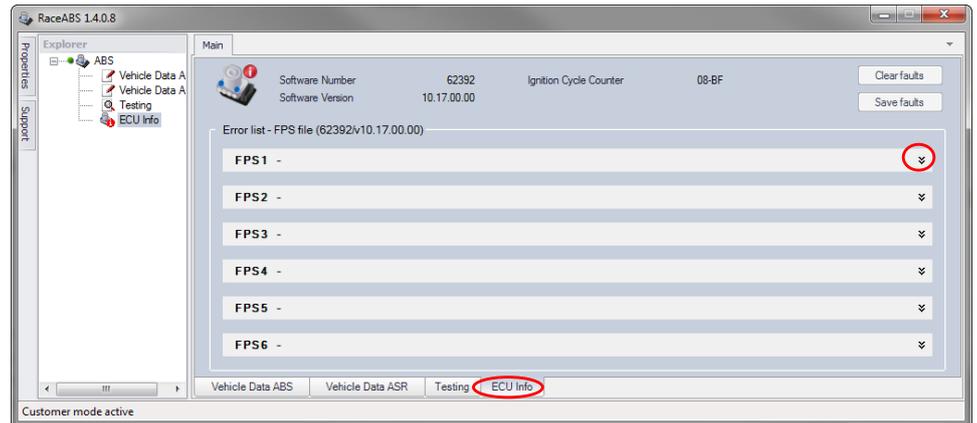
When you turn the ignition on, the ABS warning light (MIL) comes on briefly and then turns off again. This indicates the light's self-testing process. If the ABS warning light (MIL) does NOT light up when you turn the ignition on, you must establish the reason for this before taking any further action or before driving the vehicle. Maybe the light bulb is not tightened firmly.

Notice

The ABS warning light (MIL) is on permanently as long as the diagnostic tool switched on.

Error log

If the warning light (MIL) is on PERMANENTLY when you turn the ignition on or, or while driving, there is a system error. Extract the system's internal error log to analyze the error. You can access the log by clicking on "ECU Info" tab in the RaceABS software.



The following list shows the most common error log entries and their description:

Fault Number	Fault Value	Failure Channel	Failure Description	Drive Cycle Fault
0x04	0xB0	Brake Light Switch (Bis)	Bis Line Interruption	
0x03	0x16	Ecu Voltage Supply (Uz)	Spike on Uz	
0x15	0x31	CAN System Failure	CANSys - BusOff Failure CAN 0	
0x26	0x50	Yaw Rate Sensor Failure	SCMM3x: PSIP1_Signalfailure detected	
0x26	0x51	Yaw Rate Sensor Failure	SCMM3x: AY1_Signalfailure detected	
0x26	0x52	Yaw Rate Sensor Failure	SCMM3x: AX1_Signalfailure detected	
0x30	0x30	Hydraulic unit main cylinder1	Channel 1 line error Pressure Sensor MC1	
0x30	0x50	Hydraulic unit main cylinder1	Power Supply error Main Cylinder 1 Pressure Sensor	
0x42	0x90	Multi Switch	Multi Switch - Analog2 - short to GND	
0x02	0xC0	Valve Relais (Vr)	Vr off- Relais does not turn on during FSA Test (Fuse def.?)	X
0x06	0xB1	Wheel Speed Sensor Front Left	WSS FL sensor line (ASSVL: short to GND- line interruption- sensor without supply- defect sensor)	X
0x06	0xB2	Wheel Speed Sensor Front Left	WSS FL sensor line (ASSVL: short to UBatt- defect sensor)	X
0x06	0xC0	Wheel Speed Sensor Front Left	WSS FL Supply line (ASPVL: short to GND or defect sensor)	X
0x07	0xB1	Wheel Speed Sensor Front Right	WSS FR sensor line (ASSVR: short to GND- line interruption- sensor without supply- defect sensor)	X
0x07	0xB2	Wheel Speed Sensor Front Right	WSS FR sensor line (ASSVR: short to UBatt- defect sensor)	X
0x07	0xC0	Wheel Speed Sensor Front Right	WSS FR Supply line (ASPVR: short to GND or defect sensor)	X
0x08	0xB1	Wheel Speed Sensor Rear Left	WSS RL sensor line (ASSHL: short to GND- line interruption- sensor without supply- defect sensor)	X
0x08	0xB2	Wheel Speed Sensor Rear Left	WSS RL sensor line (ASSHL: short to UBatt- defect sensor)	X
0x08	0xC0	Wheel Speed Sensor Rear Left	WSS RL Supply line (ASPHL: short to GND or defect sensor)	X
0x09	0xB1	Wheel Speed Sensor Rear Right	WSS RR sensor line (ASSHR: short to GND- line interruption- sensor without supply- defect sensor)	X
0x09	0xB2	Wheel Speed Sensor Rear Right	WSS RR sensor line (ASSHR: short to UBatt- defect sensor)	X
0x09	0xC0	Wheel Speed Sensor Rear Right	WSS RR Supply line (ASPHR: short to GND or defect sensor)	X
0x15	0xA2	CAN System Failure	CANSys - Message DRS_RX_ID0Timeout	
0x15	0xA9	CAN System Failure	CANSys - Message BREMSE_6Timeout	
0x15	0xC0	CAN System Failure	CANSys - Generic	
0x26	0xA4	Yaw Rate Sensor Failure	SCMM3x reports PSIP2 Sensor NotAvailable error	
0x26	0xC5	Yaw Rate Sensor Failure	Drs - InfoTimeout	
0x26	0xD0	Yaw Rate Sensor Failure	New SCMM3x sensor detected (Ser. Nbr. CAN <- Ser. Nbr. EEPROM)	
0x42	0xA0	Multi Switch	Multi Switch - Analog2 - line fault	
0x42	0xB0	Multi Switch	Multi Switch - Analog1 - short to GND	
0x42	0xC0	Multi Switch	Multi Switch - Analog1 - line fault	
0x0A	0x80	WssGeneric	WssGeneric/generic WSS Fault due to Lambda 6 Monitor (no wheel Specific Fault detection possible)	X

Notice

Multi switch = ABS Map switch

Notice

System reset after drive cycle defaults.

Drive cycle defaults, e.g. because of wheel speed sensor bug, need an ABS-ECU reset (Power off – Power on). After the reset, the car has to accelerate to more than 12 km/h for system check.

Save error log entries

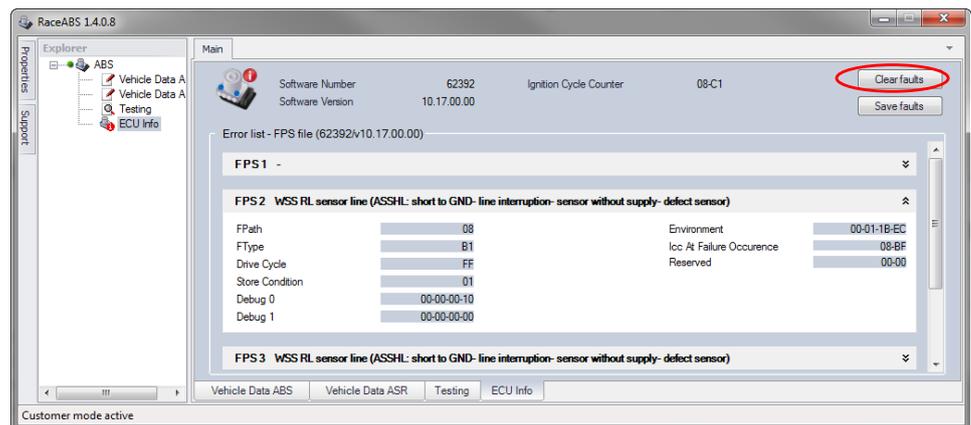
If any error log entries occur that are not listed above, please contact your dealer or the OEM customer service. Communication would be easier if you send also a copy of your error log entries. There are two possibilities to get the copy of the error log entry:

Click on the right button named "Save faults"

Click with your right mouse button into the FPS window and save the entries with click on „Save ECU-Info“.

Delete error log entries

After carrying out the problem-solving actions, delete the entry from the error log by clicking on the "Clear faults" button, as seen below:



Then turn off and on again. After you deactivated the software, the indication lamp will no longer lit.

Notice

If not all the faults are described in clear text or if there is no error description, please check if you use the correct FPS-file or contact Bosch Motorsport for update.

Ignition Cycle Counter

The ignition cycle counter shows how often you switched on the ignition. If you compare the values of the ignition cycle counter and ICC at Failure Occurrence you can trace back at what time the faults occurred. If both fields show the same values, it is an actual fault.

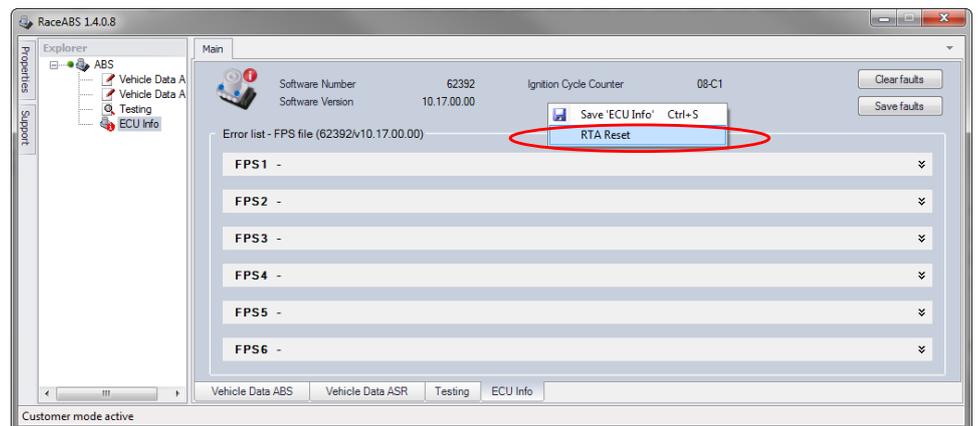
RTA Function

The RTA is a tire-tolerance-adjustment.

Due to tire quality and tire pressure, the wheels have not the same rotation speed. To compensate these differences the ABS system takes one wheel as reference and multiplies the wheel speed of each wheel with a factor so that all wheels have the same speed. By this, the ABS system can determine if the vehicle is in a curve or on straight road.

RTA Reset

To reset the factors the ABS system assigned to the wheels (all factor 1), please right-click on the button "ECU Info" and then on the button "RTA Reset". This reset is necessary e.g. if the vehicle has driven in a circle for a long time. Then the system has adapted to the cornering and considers that you are driving on a straight road.



Notice

Only execute a RTA reset if the system has adjusted (e.g. after circular driving).

Notice

Please be aware that after the RTA reset the system has to re-learn.

Drive after a RTA reset constantly with up to 100 km/h until the system has recalibrated. Drive without acceleration and without depressing the brake pedal.

See also

 Properties [29]

10 Appendix

The following chapter introduces the Startup Checklist, the CAN Protocol and the ABS_M4.dbc.

10.1 Startup Checklist

This short checklist is intended to supplement the ABS M4 Kit's manual, not replace it. Prior to using this checklist the user/installer should read the ABS manual, especially section Assembling the Parts [▶ 19] to ABS M4-Laptop Communication [▶ 26].

Basics

- Hydraulic unit with attached control unit mounted correctly (mounting plate used, brake lines facing upwards), see section Hydraulic Power Unit with attached Control Unit [▶ 19].
- Brake pressure sensor and Yaw/Acceleration sensor installed in proper locations? See section Brake Pressure Sensor [▶ 20] and Gyro/Acceleration Sensor [▶ 22].
- Everything plugged in to harness, power ring terminals connected to battery, ground ring terminals connected to solid and clean chassis ground, circuit breakers installed properly, ABS toggle switch turns off system. See section Brake Pressure Sensor [▶ 20] and Gyro/Acceleration Sensor [▶ 22].

Software Tool and Error Checking

- Connect to the ABS M4 control unit with MSA Box II using RaceABS Software and ensure that all vehicle data has been entered correctly. The vehicle data can be saved and or loaded by right clicking in the screen.

Notice

Once the diagnosis software RaceABS is connected to the harness, the ABS warning light (MIL) will light up and remain lit until it is disconnected. See section Testing [▶ 32], Step 2. If the MSA Box II is not connected to the laptop the indication lamp lightens red-yellow.

- With the system on, switch to the "ECU Info" page and clear errors with clicking on Clear FPS. Wait a moment (system will self-refresh error stack). Reset the system by switching off/on. Check if any errors reappear in the error stack. If errors reappear, diagnose errors before proceeding. If anything was unplugged during the diagnostic process, errors will be present and need to be removed from the error stack. Next, cycle ABS on/off switch and verify no errors are present after cycling power, see section ECU Info (Diagnostics) [▶ 36].

Error Notes

- CAN errors can occur if there are too many errors in the stack.
- If the wheel speed signal splitter is disconnected all four wheel speed sensors will have error entries.

Function Check

- While connected with the RaceABS software switch to the "Testing" page. Check all sensors for plausibility and proper function. Press brake pedal: brake switch bit should toggle (0->1) between 3 to 5 bar brake pressure, the display "Pressure sensor" should show a logical value. Rotate ABS map switch, the value "Multiswitch" should turn up clockwise. Manually move yaw/accelerometer sensor to the right and left as well as to the front and rear. The "Ax" and "Ay"-values should increase positive or negative analogue to the Tilt. See section Testing [▶ 32].
- Put the car on jack stands so all wheels can be freely rotated. While connected with the RaceABS software and viewing the "Testing" page, rotate each wheel and verify the correct wheel speed responds in the "Testing" page, see section Testing [▶ 32].
- Click "Pump On" button on the "Testing"-page. The pump now runs for 10 seconds or until you press the button again. After the pump shuts off, an assistant hold the brake pedal down (Please check: all wheels have to be locked!) Next, while the assistant still holds brake pedal down, click the "Release Brake" button for a given wheel (one at a time). Verify that brake releases at that wheel by rotating the wheel before clicking the next button. Repeat for each wheel.

Notice

During this release test, the pump may switch on repetitively. See chapter: Testing [▶ 32]

- On the "Testing" page now decide between the "Repair Bleeding (Tandem MC)" and "Repair Bleeding (Balanced Bar)". Click on the button "Start wizard" at the bottom right. Follow the instructions listed in the sub window in order to bleed the ABS hydraulic unit.

Notice

This will bleed the ABS hydraulic unit only, not the brake lines or the wheel brake cylinders. See chapter: Repair Bleeding Wizzard [▶ 35]

- Bleed brakes in normal fashion, starting with the furthest brake from the master cylinder and finishing with the nearest. Check errors one last time, diagnosis any errors present, then disconnect MSA Box II from ABS harness. Once MSA Box II is disconnected verify that MIL lamp turns off and stays off.
- Check for proper brake operation at low speeds first. Start with ABS map switch in a neutral position (position 5 to 7).

Notice

Refer to manual for more information regarding the ABS map switch position function. See chapter: ABS in Motorsport [▶ 5] and Features [▶ 6].

- ABS warning light (MIL) on for a short time when you switch on the ignition, on permanent when map switch in position 12 (OFF).

10.2 CAN Protocol

Name	Message	Startbit	Length (Bit)	Byte Order	Value Type	Initial Value
PSIP1 (Yaw)	0x70	0	16	Intel	Unsigned	-163,84
AY1	0x70	32	16	Intel	Unsigned	-4,1768
PSIPP (YawAcc)	0x80	0	16	Intel	Unsigned	-4096
AX1	0x80	32	16	Intel	Unsigned	-4,1768
WS_FL	0x24A	0	16	Intel	Unsigned	0
WS_FR	0x24A	16	16	Intel	Unsigned	0
WS_RL	0x24A	32	16	Intel	Unsigned	0
WS_RR	0x24A	48	16	Intel	Unsigned	0
SwitchState	0x5C0	0		Intel	Unsigned	0
P_Hz	0x5C0	8	16	Intel	Signed	0
BLS	0x5C0	24	1	Intel	Unsigned	0
EBD Lamp	0x5C0	30	1	Intel	Unsigned	0
ABS Active	0x5C0	29	1	Intel	Unsigned	0
ABS Lamp	0x5C0	31	1	Intel	Unsigned	0
AX1_Bremse60	0x5C0	32	16	Intel	Unsigned	-4,1768
AY1_Bremse60	0x5C0	48	16	Intel	Unsigned	-4,1768

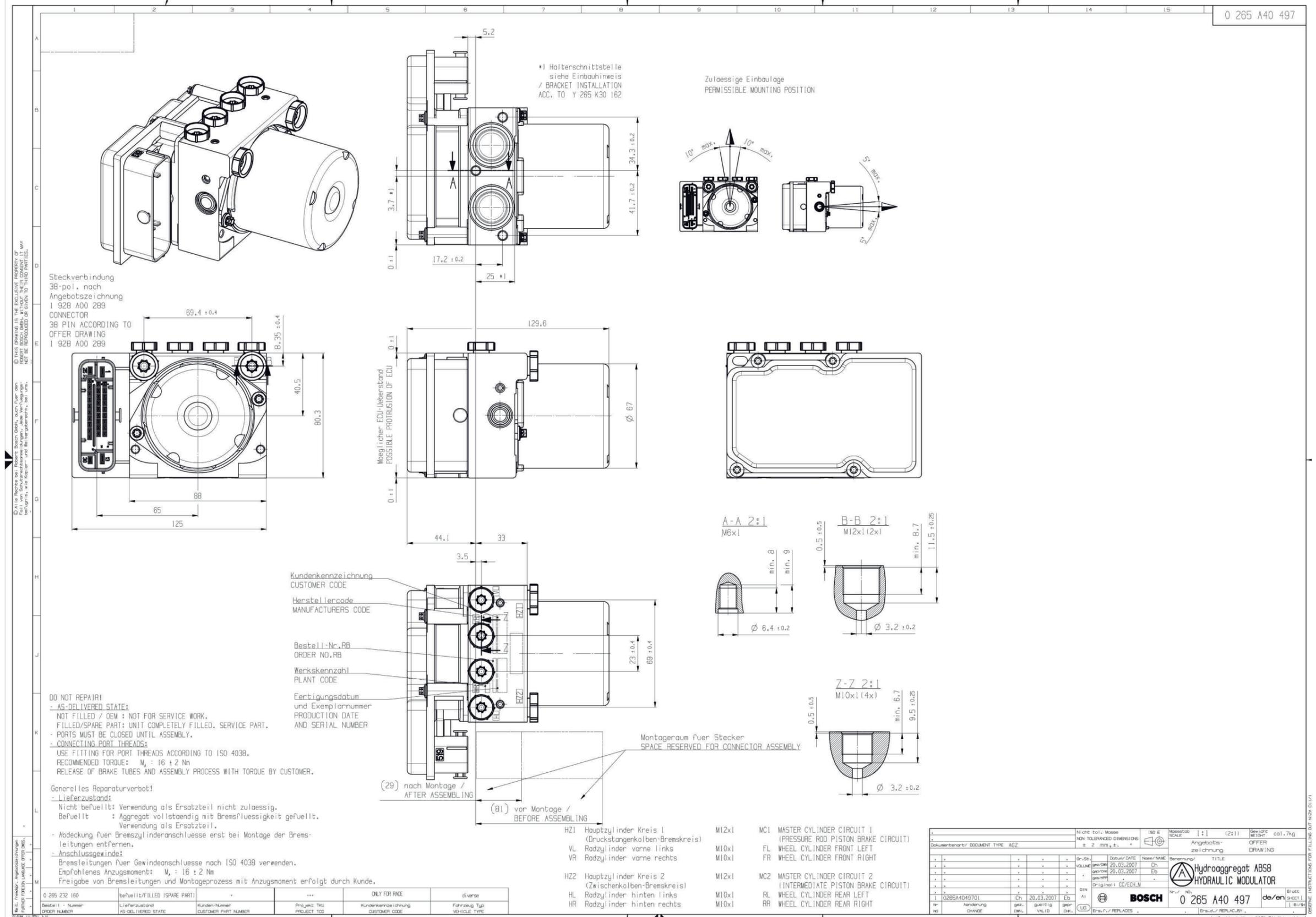
Continuation:

Name	Factor	Offset	Min	Max	Unit	Rate (ms)	Comment
PSIP1 (Yaw)	0,005	-163,84	-163,84	-163,83	°/s	10	Yaw Rate
AY1	0,00012742	-4,1768	-4,1768	-4,1765	g	10	Lateral Acceleration (Ay)
PSIPP (YawAcc)	0,125	-4096	-4096	-4095	°/s	10	Yaw Acceleration
AX1	0,00012742	-4,1768	-4,1768	-4,1765	g	10	Longitudinal Acceleration (Ax)
WS_FL	0,015625	0	0	100	m/s	10	Wheel Speed Front Left
WS_FR	0,015625	0	0	100	m/s	10	Wheel Speed Front Right
WS_RL	0,015625	0	0	100	m/s	10	Wheel Speed Rear Left
WS_RR	0,015625	0	0	100	m/s	10	Wheel Speed Rear Right
SwitchState	1	0	0	12		10	ABS Map Switch Position
P_Hz	0,0153	0	-42,5	425	bar	10	Brake Pressure
BLS	1	0	0	1			Brake Light Switch
EBD Lamp	1	0	0	1			EBD Fault Lamp
ABS Active	1	0	0	1			ABS Active Bit
ABS Lamp	1	0	0	1			ABS Fault Lamp
AX1_Bremse60	0,00012742	-4,1768	-4,1768	-4,1765	g	10	Longitudinal Acceleration (Ax)
AY1_Bremse	0,00012742	-4,1768	-4,1768	-4,1765	g	10	Lateral Acceleration (Ay)

To avoid redundant messages while connecting the ABS-CAN to the vehicle-CAN, please keep in mind that the ABS system sends further messages as follows:

0x140	0x340	0x542	0x75
0x141	0x341	0x560	0x80
0x142	0x342	0x576	
0x143	0x343	0x5C0	
0x24A	0x541	0x70	

11 Offer Drawing: Hydraulic Power Unit with attached Control Unit



12 Offer Drawing: Brake Pressure Sensor

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Kabelbaumstecker: RB-Kompaktstecker 1.1a nach RB-Zeichnung A 928 000 453, 3-polig, Kodierung 1, BDK-Kontakte vergoldet, 0.5-1.0mm²

WIRE HARNESS CONNECTOR : RB KOMPAKT CONECOR 1.1A ACC. TO RB DRAWING A 928 000 453, 3 PINS, CODING 1. BDK TRMINALS GOLD-PLATED, 0.5-1.0 mm²

Am Sensor: RB-Kompaktstecker 1.1 nach RB-Zeichnung D 928 002 69A in hochschuettelfester Ausführung 3-polig, Kodierung 1, Kontakte vergoldet Werkstoff: PBT GF30

AT SENSOR: RB KOMPAKT CONNECTOR 1.1 IN HIGH VIBRATION RESISTANT DESIGN ACC. TO RB DRAWING D 928 002 69A 3 PINS, CODING 1, TERMINALS GOLD-PLATED MATERIAL: PBT GF30

0 261 A04 407

Pin 3: Versorgung (+)
Pin 3: SUPPLY VOLTAGE (+)

Pin 2: Ausgang
Pin 2: OUTPUT

Pin 1: Masse (-)
Pin 1: GROUND (-)

Werkstoff: 1.4104 (DIN Norm)
MATERIAL: 1.4104 (DIN Norm)

Herkunftsbezeichnung
MARKING OF ORIGIN

Auf der Ruckseite:
ON THE BACK:

Werknummer
NUMBER OF PLANT

Typ-Aufschrift
TYPE DESIGNATION

Fertigungsdatum
nach Bosch-Norm
N41A4-2.3
und Seriennummer
DATE OF PRODUCTION
ACC. TO BOSCH
STANDARD N41A4-2.3
AND SERIAL NUMBER

Stanzeinzug max. 0.6
STAMP PULL-IN MAX. 0.6

Wichtige Hinweise:

- RB-Gewährleistung fuer die Funktion des Stecksystems nur bei Verwendung der in dieser Angebotszeichnung vorgeschriebenen Gegenstecker-Systemteile.
- Erste Abstuetzstelle des Kabels max. 150mm nach der Steckverbindung (gestreckte Kabellänge). Sie muss auf dem Sensortraeger liegen.
- Abwicklung des Kabels (Abweichung von der geraden Linie) zwischen Kabelabgang am Sensor und erster Abstuetzstelle: 20...90°
- Zulaessiger Biegeradius des Kabels bis zur ersten Abstuetzstelle: R ≥ 50mm
- Einbauvorschrift siehe zugehoerige Railangebotszeichnung bzw. Rail-TKU
- Max. zulaessige Einschraubbelastung: 35Nm
- Montagehinweis siehe Y 261 F26 048

Zu beachten: Sensor ist durch aufgesteckten Gegenstecker vor Eindringen von Wasser zu schuetzen.

IMPORTANT NOTES

- RB WARRANTY WILL COVER THE FUNCTION OF THE CONNECTOR SYSTEM ONLY IN CASE OF COMBINATION WITH HARNESS CONNECTOR SYSTEM PARTS ACCORDING TO THIS OFFER DRAWING.
- FIRST CABLE MOUNTING POINT MAX. 150 MM AFTER THE PLUG (STRAIGHT CABLE LENGTH). IT MUST BE LOCATED ON THE SENSOR CARRIER.
- ANGLE OF BENDING THE CABLE (DEVIATION FROM STRAIGHT LINE) BETWEEN CABLE EXIT AT SENSOR AND FIRST MOUNTING POINT: 20...90°.
- ADMISSIBLE BENDING RADIUS OF THE CABLE UP TO THE FIRST CABLE MOUNTING POINT: R ≥ 50MM.
- INSTALLATION INSTRUCTIONS SEE CORRESPONDING OFFER DRAWING RAIL RESPECTIVELY TKU RAIL
- MAX. AUTHORIZED STRESS TO SCREW IN: 35Nm
- ASSEMBLY INSTRUCTIONS SEE Y 61 F26 048

ATTENTION: USE HARNESS CONNECTOR FOR PROTECTION AGAINST WATER INGRESS.

Stutzen nach unten gerichtet.
Empfohlene Lage: 0...90°
in allen Richtungen zur Senkrechten.
ORIFICE DIRECTED DOWNWARDS.
RECOMMENDED POSITION: 0...90°
FROM VERTICAL.

Dokumententyp/ DOCUMENT TYPE AGZ		Nicht tol. Masse NON TOLERANCED DIMENSIONS ±1 mm, ±5 °		ISO E		Maßstab SCALE 2:1 1:1		Gewicht WEIGHT 35,3 g	
						Angebots- zeichnung DRAWING			
		Gr.-St. VOLUME		Datum/ DATE 24.02.2005		Name/ NAME De		Benennung/ TITLE	
								RAIL PRESSURE SENSOR DS-HD-KV4.2, 26 MPa	
				Original: GS-SI/ENS				N ^o . / NO.	
				DIN A2		BOSCH		0 261 A04 407 de/en	
N ^o / NO.		Aenderung CHANGE		gez. DIN.		gueltig VALID		gepr. CHK.	
				Ers.f./ REPLACES		Ers.d./ REPLAC.BY		Blatt SHEET 1	

Entwicklungsnummer DEVELOPMENT NUMBER	0 261 B08 072 06 Bestell - Nummer ORDER NUMBER	Typ - Aufschrift TYPE DESIGNATION	0 261 K00 109 Datenblatt (TKU) DATA SHEET
--	--	--------------------------------------	---

13 Mounting Instructions: Brake Pressure Sensor

Bosch Gasline Systems, P81 | 2703373053 DRW 001 03 | SAP-Status 40 | Labor F28 | Change F030GD000901

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Weitere Fremdspr.-Zeichnungen FURTHER FOREIGN LANGUAGE DINGS

ISO-Grenzmasse/ ISO LIM. OF SIZE		
Mass/ SIZE ueber bis OVER TO	Toleranzklasse TOL. CLASS	Grenzabmasse LIM. DEVIATIONS
.	.	.
.	.	.
.	.	.
.	.	.
.	.	.
.	.	.
Rauheitsang. *DIN EN ISO 1302 (NI2A D53/1) SURF. ROUGHN.		
Kanten *DIN ISO 13715 (NI2A B42) EDGES		
+0.3 -0.3 (03)		
Metr. ISO	ohne Oberfl. W/O SURFACE	mit Oberfl. WITH SURFACE
Aussengewinde EXT. THREAD	.	.
Innengewinde INT. THREAD	.	.
Nicht tolerierte Masse NON TOLERANCED DIMENSIONS		
0.5 ...3	> 3 ...6	> 6 ...30
> 30 ...120	> 120 ...400	> 400 ...1000
± 0.1	± 0.1	± 0.2
± 0.2	± 0.3	± 0.5
± 0.5	± 1	± 1
Rundungen, Fasen RADII, CHAMFERS		
± 0.2	± 0.5	± 1
± 1	± 1	± 1
Winkel, Masse der kuerzeren Schenkel ANGLES, DIM. OF THE SHORTER SIDE		
bis 10	> 10 ...50	> 50 ...120
> 120 ...400	> 400 ...1000	> 1000 ...10000
± 1'	± 30'	± 20'
± 10'	± 10'	± 5'
Form- und Lagetoleranzen TOLERANCES OF FORM AND POSITION		
DIN ISO 2768-H (NI3 B92/1)		
Stoffe entsprechen N2580 MATERIALS CORRESPOND TO N2580		

Frei von Öl, Fett und Rückständen
FREE OF OIL, GREASE AND RESIDUALS

Während Lagerung und Transport vor Verschmutzung schützen
SAVE AGAINST CONTAMINATION DURING STORAGE AND TRANSPORTATION

Fehl. Angaben/ MISS. DETAILS		Oberfläche SURFACE		Mastab SCALE 2:1 (5:1 1:1)		Gewicht WEIGHT									
1. Verwendung/ 1ST APPLICAT.		Stoff/MAT'L		aus/ FROM siehe Stueckliste		Benennung/ TITLE									
Dokumententyp/ DOCUMENT TYPE DRW		Original: NuPI/TEF610		BOSCH Nr./ NO. 2 703 373 053 de/en		Blatt SHEET 1									
Stueckliste besonderes Blatt/ PARTS LIST ON SEPARATE SHEET		Original: NuPI/TEF610				Bl/SH									
<table border="1" style="font-size: 6px;"> <tr> <th>Gr. St.</th> <th>Datum/ DATE</th> <th>Name/ NAME</th> </tr> <tr> <td>03</td> <td>04.06.2007</td> <td>WR</td> </tr> <tr> <td>02</td> <td>28.03.2008</td> <td>WR</td> </tr> <tr> <td>01</td> <td>04.06.2007</td> <td>WR</td> </tr> </table>		Gr. St.	Datum/ DATE			Name/ NAME	03	04.06.2007	WR	02	28.03.2008	WR	01	04.06.2007	WR
Gr. St.	Datum/ DATE	Name/ NAME													
03	04.06.2007	WR													
02	28.03.2008	WR													
01	04.06.2007	WR													

14 Offer Drawing: Wheel Speed Sensor

0 265 A02 324-718

Impulsrad Drehrichtung
TABLET WHEEL ROTATION DIR.

Signalabgriffsfleche
SENSING SIDE

O-Ring F 00C 118 915
O-RING F 00C 118 915

Fertigungsdatum
PRODUCTION DATE

Markierung zur Lage des ICs
MARK FOR POSITION OF IC

Werkstoffnummer
PLANT CODE NUMBER

Position Sensorelemente
POSITION SENSOR ELEMENTS

Materialkennung
MATERIAL IDENTIFICATION

Kunststoff darf nicht ueber Buchsenkante ueberstehen
PLASTIC MUST NOT PROTRUDE OVER BUSHING EDGE

Abriebfester Aufdruck von Kunden Sach-Nr (siehe Tabelle)
Robert Bosch Sach-Nr (siehe Tabelle) gegenueberliegend der Kunden Sach-Nr am Umfang um 180° versetzt.
ABRASION RESISTANT PRINT WITH CUSTOMER PART-NO (SEE TABLE) ROBERT BOSCH PART-NO (SEE TABLE) OPPOSITE TO THE CUSTOMER PART-NO ON CIRCUMFERENCE APPROX. 180° APART.

Kabelstecker F 00C 160 001
(Details siehe A 285 561 574)
CABLE CONNECTOR F 00C 160 001
(DETAILS SEE A 285 561 574)

Schuttschlauch F 00C 116 461
PROTECTING TUBE F 00C 116 461

Tuelle F 00C 118 413
GROMMET F 00C 118 413

Clip F 00C 118 736
CLIP F 00C 118 736

M 1:1
SCALE 1:1

Material/MATERIAL

Gehäuse: Polyamid waerme-stabilisiert
HOUSING: POLYAMIDE HEAT STABILIZED

Leitung: Mantelleitung zweiadrig
Aussen Ø : 5,0±0,3;
Mantelisolierung: Polyurethan-Elastomer 95:5 Shore A.

CABLE: MOLDED CABLE COVER
TWO CORES, D_c = 5,0±0,3
COVER INSULATION: POLY-URETHANE ELASTOMER 95:5 SHORE A.

Buchse: Stahl
BUSHING: STEEL

3-D Ansicht
3-D VIEW

Bosch Wertmarke
BOSCH LOGO TYPE

Bosch Bildmarke
BOSCH SYMBOL

Herkunftsland
COUNTRY OF ORIGIN

Ansicht A
VIEW A

Kontakt 1:
An schwarzer Ader fuer Signal (-)
CONTACT 1:
ON BLACK CORE FOR SIGNAL (-)

Kontakt 2:
An weisser Ader fuer Versorgungsspannung (+)
CONTACT 2:
ON WHITE CORE FOR SUPPLY VOLTAGE (+)

Kein Verpolschutz !
NO REVERSE POLARITY PROTECTION !

Mass durch Auswahlpruefung absichern
TO BE CHECKED IN QUALITY TEST

Allgemeiner Hinweis:
Achtung! Dieser Drehzahlfuehler enthaelt ein elektronisches Bauteil und kann somit potentiell durch elektrostatische Entladung beschadigt werden. Die Handhabungsvorschriften fuer elektrostatisch empfindliche Bauteile sind einzuhalten.

GENERAL REMARK:
WARNING! THIS WHEEL SPEED SENSOR CONTAINS AN ELECTRONIC COMPONENT THAT CAN POTENTIALLY BE DAMAGED DUE TO ELECTROSTATIC DISCHARGE. REFER TO THE OPERATING INSTRUCTION FOR PROPER HANDLING OF ELECTROSTATICALLY SENSITIVE COMPONENTS.

Achtung Dauermagnet!
ATTENTION PERMANENT MAGNET!

Temperaturzonen (siehe Datenblatt)
TEMPERATURE ZONES (SEE DATA SHEET)

Kabelzone
CABLE ZONE

Sensorenzone
SENSOR ZONE

Lage der Sensorkopfbeschriftung kann von Zeichnung abweichen.
POSITION OF SENSORHEAD MARKINGS MAY BE DIFFERENT FROM THIS DRAWING

Drehzahlfuehler darf erst unmittelbar vor der Montage in das Fahrzeug oder vor Einbau in die Pruefvorrichtung aus der Verpackung gezogen werden. Montage des Drehzahlfuehlers erfolgt durch Eindruetzen von Hand bis auf Anschlag, vor dem Festschrauben. Vor wiederholter Montage des DFs ist der montierte O-Ring durch einen neuen O-Ring zu ersetzen.

SPEED SENSOR MAY BE REMOVED OF ITS PACKAGING ONLY IMMEDIATELY BEFORE THE INSTALLATION INTO THE VEHICLE OR INTO THE TEST DEVICE. THE SENSOR IS TO BE MOUNTED BY PUSHING INTO PLACE BY HAND, UNTIL STOP, BEFORE FIXING OF SCREW. BEFORE RE-MOUNTING THE WSS, THE INSTALLED O-RING HAS TO BE REPLACED BY A NEW O-RING.

Einbauempfehlung:
Befestigung mit partiell mikroverkapselter Zylinderschraube M6 DIN 912-8.8
Anziehdrehmoment: 8±2Nm
Entsprechende Impulsradspezifikation beachten!
Zulaessige magnetische Fremdfelder: siehe TKU

INSTALLATION RECOMMENDATION:
FIX WITH PARTIALLY SELF-SEALING CYLINDRICAL SCREW M6 DIN 912-8.8
TIGHTENING TORQUE: 8±2Nm
SEE CORRESPONDING TRIGGER RING SPECIFICATION!
PERMISSIBLE STRAY MAGNETIC FIELDS: SEE TKU

0 265 992 324		0 265 007 871		0 265 100 017		m-Zeichnung / OVER DRAWING		VA re / FRONT RIGHT		4302		170324	
Beschreibung / Description		Detail - Nummer / Detail NUMBER		Typ / TYPE		Detailstatus / DATA SHEET		Befestigungsfleche / FIXING PLATE		Einbaueinfach / INSTALLATION		CS-18-Nr. / CUSTOMER NO.	

AGZ 0265A02324-718 BI. 01 27.04.2006 Änd. 002

BhP/DocMaster-Original, neuestes Dokument am 14.02.07

LKS25I

15 Offer Drawing: Gyro/Acceleration Sensor

0 274 A00 305

Steckerbelegung PIN CONFIGURATION	
PIN 1	GND
PIN 2	CANL
PIN 3	CANH
PIN 4	UBAT

Einbaort: Nahe des Fahrzeugschwerpunktes. Anderer Einbaort nach Zustimmung durch RB FDR-Systementwicklung moeglich.
MOUNTING LOCATION: CLOSE TO CENTER OF GRAVITY OF VEHICLE. OTHER MOUNTING LOCATION AFTER AUTHORISATION BY RB-FDR SYSTEM DEVELOPMENT POSSIBLE.

(Einbau entgegen der Fahrtrichtung oder Ueberkopf-Montage nach Zustimmung durch RB FDR-Systementwicklung moeglich).
(MOUNTING OPPOSITE TO DRIVING DIRECTION OR OVERHEAD MOUNTING AFTER AUTHORISATION BY RB-FDR SYSTEM DEVELOPMENT POSSIBLE).

Zulaessige Abweichung der Referenzachse quer zur Fahrtrichtung $\pm 3^\circ$
PERMISSIBLE DEVIATION OF REFERENCE AXIS PERPENDICULAR TO DRIVING DIRECTION $\pm 3^\circ$.

Zulaessige Abweichung von Fahrzeug Z-Achse zur Referenzflaeche $\pm 3^\circ$
PERMISSIBLE DEVIATION OF REFERENCE SURFACE TO VEHICLE Z-AXIS $\pm 3^\circ$.

Sensor in Einbaulage dargestellt
SENSOR SHOWN IN MOUNTING POSITION

Buchsenflaeche muss vollstaendig aufliegen.
BUSHING SURFACE MUST BEAR ON COMPLETELY.

Max. Winkelabweichung der Anschraubbolzen in x- und y-Richtung: 2.2°
MAX. ANGULAR DEVIATION OF THE MOUNTING BOLTS (X- AND Y-DIRECTION): 2.2°

Die Einbau- und Umgebungsbedingungen gemass der technischen Kundenunterlagen (TKU, siehe Tabelle) sind einzuhalten.
THE MOUNTING AND ENVIRONMENTAL CONDITIONS ACCORDING TO THE TECHNICAL CUSTOMER DOCUMENTATION (TKU, SEE TABLE BELOW) ARE TO BE FULFILLED.

Anziehdrehmoment fuer Mutter/Schraube M6 = $6Nm +2Nm / -1Nm$
Max. zulaessige Axialkraft: 12 kN
FIXING-TORQUE FOR NUT/SCREW M6 = $6Nm +2Nm / -1Nm$
MAX. PERMITTED AXIAL LOAD: 12 kN

Schraubpartner muessen ausreichende Anpressflaeche aufweisen, fuer zul. Anziehdrehmoment ausgelegt sein und ausreichende Korrosionsbestaendigkeit aufweisen.
FIXATION COUNTERPARTS MUST HAVE SUFFICIENT PRESSING SURFACE, MUST BE DIMENSIONED FOR PERMISSIBLE FIXATION TORQUE AND MUST HAVE SUFFICIENT CORROSION RESISTANCE.

Anschraubprozess des Sensors liegt in Kundenverantwortung. Bei Fehlmontage keine RB-Gewaehrleistung.
FIXATION PROCESS OF THE SENSOR IS WITHIN CUSTOMERS RESPONSIBILITY. IN CASE OF POOR MOUNTING NO RB-WARRANTY.

Gewaehr fuer die zuverlaessige Funktion des Stecksystems nur bei Verwendung des von RB vorgeschriebenen Gegensteckers. RB WARRANTY COVERS RELIABLE FUNCTION OF THE CONNECTOR SYSTEM ONLY IF A WIRING HARNESS-SIDE CONNECTOR SPECIFIED BY RB IS UTILIZED

Im Bereich der Auflageflaeche des Sensors $\square 0.2$
(Umriess Gehaeuse + Gegenstecker)
IN SUPPORTING SURFACE AREA OF THE SENSOR $\square 0.2$
(HOUSING + SOCKET HOUSING OUTLINE)

Sonderzubehoer:	ADDITIONAL PARTS:
Gehoert nicht zum Lieferumfang, muss gesondert bestellt werden.	NOT INCLUDED IN SCOPE OF DELIVERY. MUST BE ORDERED SEPERATELY.
Buchsengehaeuse TYCO/AMP Best.-Nr. 1-967640-1	CONNECTOR HOUSING TYCO/AMP ORDER-NO. 1-967640-1
Buchsenkontakt (4 Stueck erforderlich) TYCO/AMP Best.-Nr. 965906-1 (IDGB 0.75mm ²)	TERMINAL (4 REQUIRED) TYCO/AMP ORDER-NO. 965906-1 (IDGB 0.75mm ²)
Einzeladerabdichtung (4 Stueck erforderlich) TYCO/AMP Best.-Nr. 967067-1 (fuer $\varnothing 1.4...1.9$)	WIRE SEAL (4 REQUIRED) TYCO/AMP ORDER-NO. 967067-1 (fuer $\varnothing 1.4...1.9$)

Einzelheit X
DETAIL X
M 4:1

Stecker:
CONNECTOR:
AMP 114-18063-076
MQS Code A
Rev. A3/25.06.01
PIN AMP Spec.
MQS 114-18063
Rev. B6/03.05.02

Steckervernastung:
CONNECTOR ENGAGEMENT:
TYCO C-208-15641
Rev. 0/25.04.03

Einzelheit Y
DETAIL Y
M 4:1

Steckermitte
CENTER OF CONNECTOR

Fahrtrichtung
DRIVING DIRECTION

Buchse, Edelstahl V2A (1.4301)
BUSHING, HIGH GRADE STEEL V2A (1.4301)

Typ-Aufschrift
TYP-DESIGNATION

Kundennummer
CUSTOMER PART NUMBER

Fertigungsdatum
MANUFACTURING DATE

Chargen-Nr.
NUMBER OF LOT

Referenzachse
(quer zur Fahrtrichtung)
REFERENCE AXIS
(PERPENDICULAR TO DRIVING DIRECTION)

PBT GF30 weiss/WHITE

PBT GF30 schwarz/BLACK

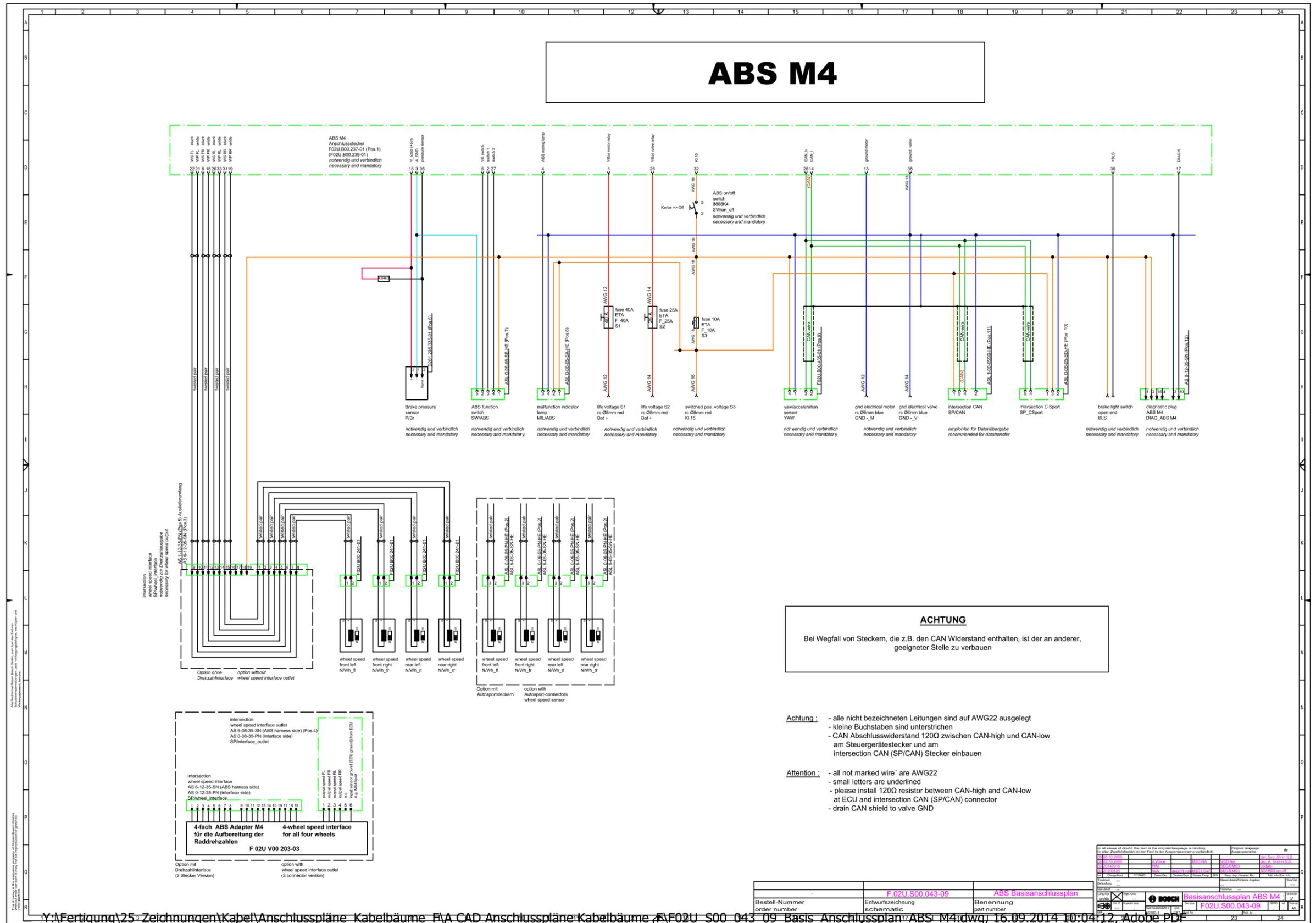
Produktionslabel mit Barcode
PRODUCTION LABEL WITH BARCODE

Teilschnitt A-A
SECTION A-A

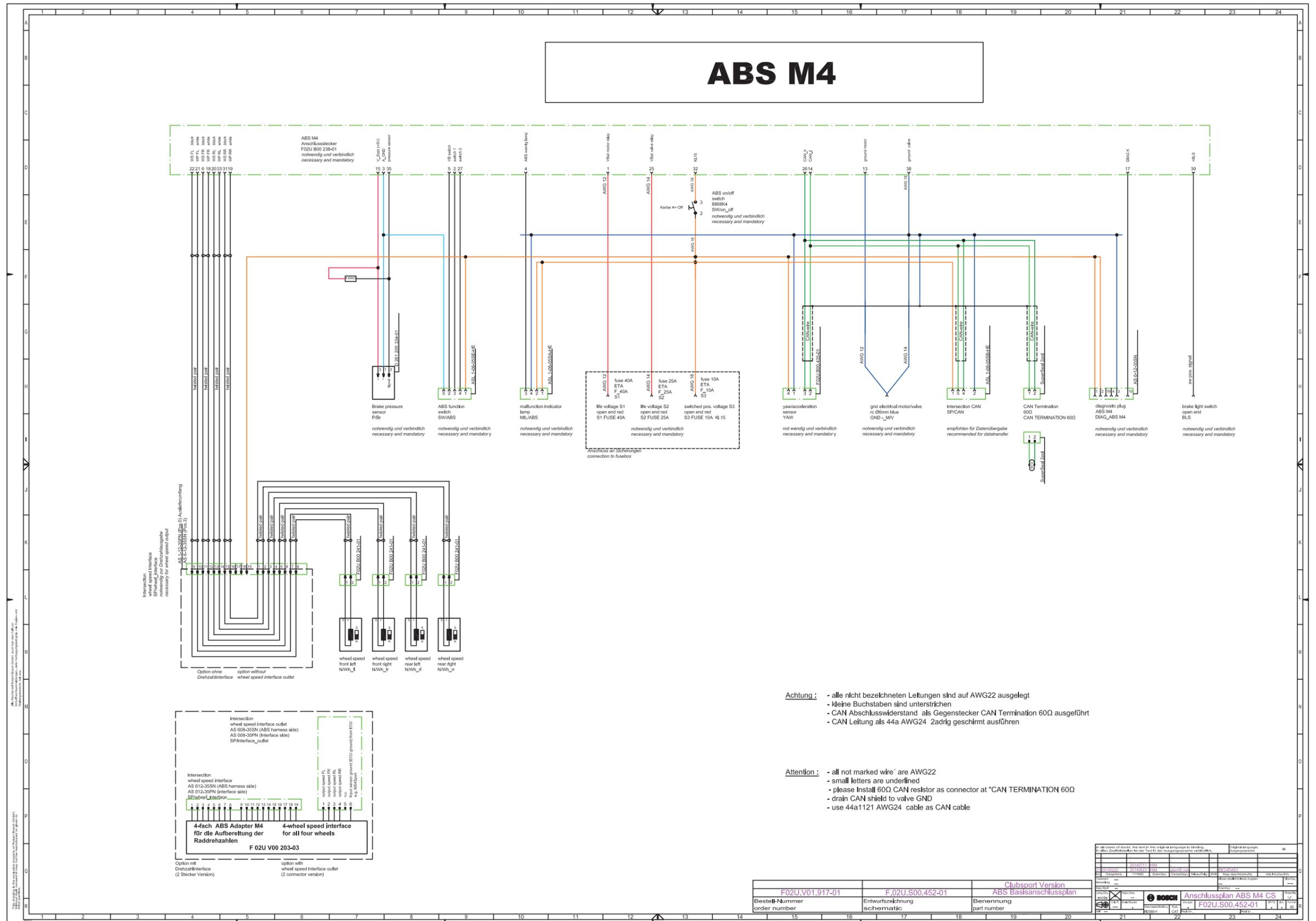
Referenzflaeche
REFERENCE SURFACE

SC MM3.xx		Nicht tol. Masse NON TOLERANCED DIMENSIONS ± 1 mm, ± 1°		Vergrößerung 1:1	Verkleinerung 4:1	Gewicht WEIGHT ~70g
0	274 A00 305	AGZ				
Angebotszeichnung OFFER DRAWING						
Drehratesensor MM3.8k YAW RATE SENSOR MM3.8k						
BOSCH						

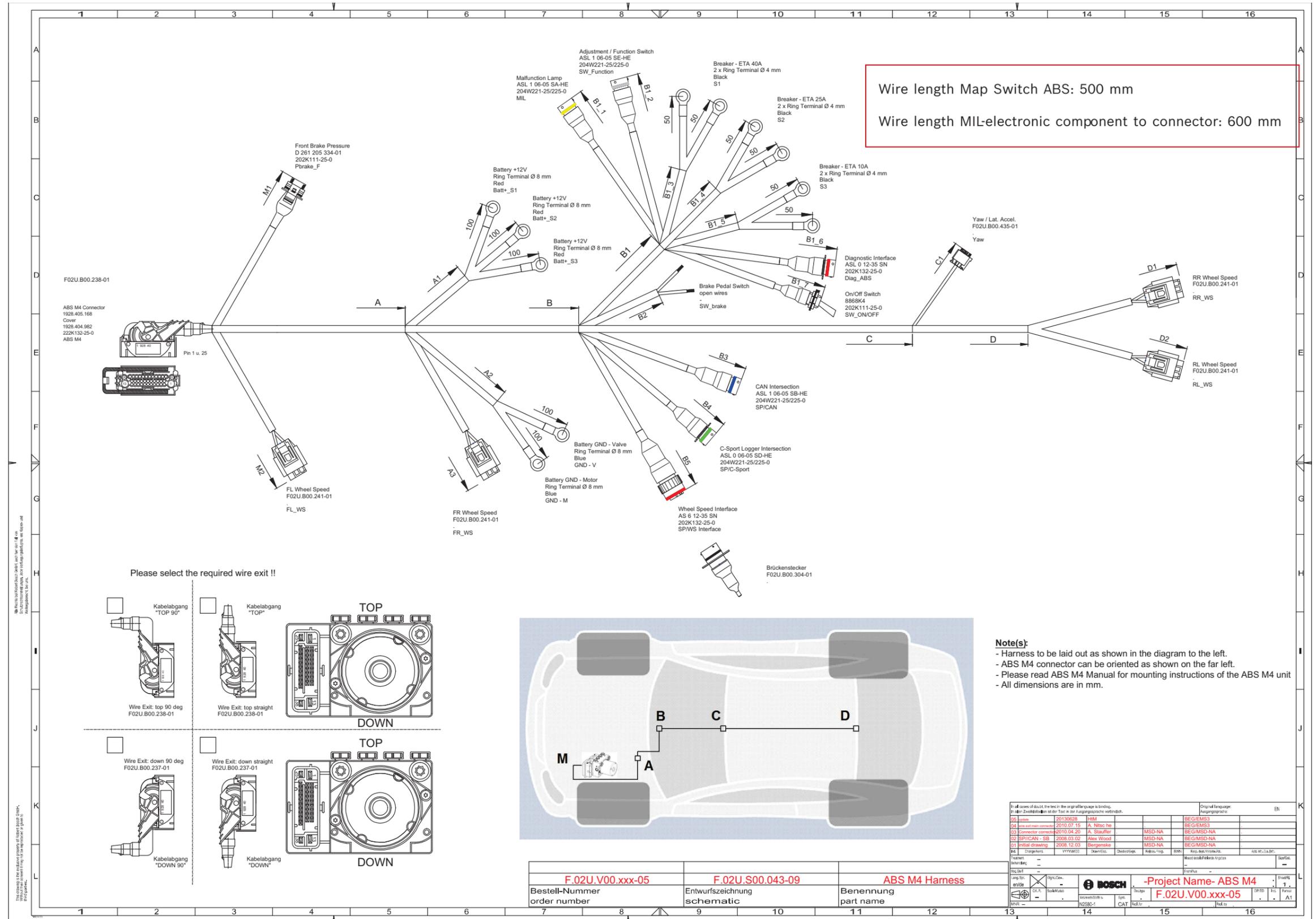
16 Wiring Diagram ABS M4



17 Wiring Diagram ABS M4 Clubsport



18 Wiring Harness in general



Bosch Engineering GmbH
Motorsport
Robert-Bosch-Allee 1
74232 Abstatt
Germany
www.bosch-motorsport.com
